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1 A novel multi-perspective imaging platform (M-PIP) for phenotyping soybean root crowns in the
2 field increases throughput and separation ability of genotype root properties

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15 **Abstract**

16 Background: Root crown phenotyping has linked root properties to shoot mass, nutrient uptake, and
17 yield in the field, which increases the understanding of soil resource acquisition and presents
18 opportunities for breeding. The original methods using manual measurements have been largely
19 supplanted by image-based approaches. However, most image-based systems have been limited to one
20 or two perspectives and rely on segmentation from grayscale images. An efficient high-throughput root
21 crown phenotyping system is introduced that takes images from five perspectives simultaneously,
22 constituting the Multi-Perspective Imaging Platform (M-PIP). A segmentation procedure using the
23 Expectation-Maximization Gaussian Mixture Model (EM-GMM) algorithm was developed to
24 distinguish plant root pixels from background pixels in color images and using hardware acceleration
25 (CPU and GPU). Phenes were extracted using *MatLab* scripts. Placement of excavated root crowns for
26 image acquisition was standardized and is ergonomic. The M-PIP was tested on 24 soybean [*Glycine*
27 *max* (L.) Merr.] cultivars released between 1930 and 2005 .

28 Results: Relative to previous reports of imaging throughput, this system provides greater throughput
29 with sustained rates of 1.66 root crowns min⁻¹. The EM-GMM segmentation algorithm with hardware
30 acceleration was able to segment images in 10 s, faster than previous methods, and the output images
31 were consistently better connected with less loss of fine detail. Image-based phenes had similar
32 heritabilities as manual measures with the greatest effect sizes observed for Maximum Radius and Fine
33 Radius Frequency. Correlations were also noted, especially among the manual Complexity score and
34 phenes such as number of roots and Total Root Length. Averaging phenes across perspectives

35 generally increased heritability, and no single perspective consistently performed better than others.
36 Angle-based phenes, Fineness Index, Maximum Width, Holes, Solidity and Width-to-Depth Ratio were
37 the most sensitive to perspective with decreased correlations among perspectives.

38 Conclusion: The substantial heritabilities measured for many phenes suggest that they are potentially
39 useful for breeding. Multiple perspectives together often produced the greatest heritabilities, and no
40 single perspective consistently performed better than others. Thus, as illustrated here for soybean,
41 multiple perspectives may be beneficial for root crown phenotyping systems. This system can
42 contribute to breeding efforts that incorporate under-utilized root phenotypes to increase food security
43 and sustainability.

44 Keywords: Multi-camera, High-throughput phenotyping, root architecture, water use, fertilizer

45 **Background**

46 The global population is expected to increase to nine billion people by 2050 which necessitates an
47 increase in global food production of at least 60%, but likely as much as 100% due to increased
48 livestock production (Grafton et al. 2015). Soybean [*Glycine max* (L.) Merr.] is one of the major crops
49 with a total global production of 351.32 million tons in 2016 (USDA 2018). Roots are crucial for plant
50 productivity by foraging in soil for water and nutrients (Lynch 1995), yet have not been major targets
51 of breeding efforts because a significant knowledge gap remains about specific relationships of root
52 form and function with yield. Improving research capacity to measure root phenes, or elemental units
53 of phenotype [1], could have major effects on breeding targets in soybean and other crops.

54 Advances in imaging and computing technologies have allowed efficient analysis of plant root images
55 (Pound et al. 2013; Lobet et al. 2011). These methods use algorithms ranging from the more complex
56 such as the EM-GMM algorithm (Dempster et al. 1977; Bilmes 1998) to simpler procedures to generate
57 segmented images such as intensity thresholding (Colombi et al. 2015; Bucksch et al. 2014; Yugan and
58 Xuecheng 2010; Huang et al. 1992). The segmented image may then be analyzed to extract root
59 phenes. For example, Janusch et al. (2014) proposed to identify root topology using Reeb graphs,
60 which depicts the topological structure of the root shape as the connectivity of level sets. Chen et al.
61 (2006) described a method to determine the branching structure in wheat using Markov chains, where
62 the lateral root branching probability was found using the locations of the lateral roots along the main
63 root. However, these methods need relatively simple root systems to extract properties with accuracy.
64 Mairhofer et al. (2012) and Zhou et al. (2014) described methods to perform 3D reconstructions from
65 X-ray computed tomography by scanning the image stack vertically. Ying et al. (2011) performed
66 reconstruction on RGB images using the regularized visual hull algorithm. Although complex root
67 system architectures were successfully identified by the tool, the procedure is still computationally
68 intensive and the image acquisition methods are not high-throughput. Plant roots grown in a gel
69 medium were imaged while revolving on a turntable, yielding 3D phenotypes (Iyer-Pascuzzi et al.
70 2010; Clark et al. 2011). Pantalone et al. (1996) showed a relationship between drought tolerance and
71 the level of complexity (fibrousness) of the root system. This work also tried to assign a root score to
72 various root systems depending upon several factors such as the amount of fibrous root, and the size

73 and number of root nodules. Topp et al. (2013) imaged rice root systems grown in clear gellan gum
74 over a full rotation in order to reconstruct 3D models and extracted both 2D and 3D phenes.

75 Software exist that analyze root growth such as KineRoot (Basu et al. 2007) and ArchiSimple (Pagès et
76 al. 2014) and using displacement vector fields (Kirchgessner et al. 2001). Balestri et al. (2015)
77 discussed the changes in the root topology when a seagrass was grown in different soil conditions
78 quantitatively. Further studies include modeling of roots (Jia et al. 2010), analysis of growth of roots in
79 time series (Fang et al. 2009), imaging the roots by parts and stitching them (Kun et al. 2011) and
80 estimation of root system architecture by modeling root length or number of roots per unit volume or
81 root density (Dupuy et al. 2005).

82 Recently, two novel strategies were proposed for high-throughput phenotyping of plant roots, Digital
83 Imaging of Root Traits (*DIRT*) (Bucksch et al. 2014) and Root Estimator for Shovelomics Traits
84 (*REST*) (Colombi et al. 2015). The procedures consist of a root imaging standard methodology for
85 excavated root crowns followed by image processing, phene extraction and analysis of the extracted
86 phenes. The *DIRT* platform was meant to be robust enough to analyze images from various imaging
87 methods and light conditions, while *REST* used an optimized imaging system using a blackout tent and
88 flash lighting to produce easily segmentable images. These systems built on the recent innovations of
89 manually scoring root crowns, sometimes called ‘shovelomics’ (Trachsel et al. 2011). In general
90 botanical terminology, root crown refers to the site where the root system transitions to the shoot
91 (Beentje 2010), and in the root phenotyping context root crown has generally been accepted to refer to

92 both the crown itself and the entirety of attached roots following excavation. That is, the root crown is
93 the top portion of the root system that remains after excavation and removal of soil by washing or other
94 means. Root crown properties have been linked to crop performance, such as nodal root number
95 (Saengwilai et al. 2014; York et al. 2013; York and Lynch 2015) and growth angle (Trachsel et al.
96 2013; York et al. 2015). The application of root crown phenotyping for legumes has recently been
97 accomplished in common bean, soybean, and cowpea (Burrige et al. 2016a; Burrige et al. 2016b;
98 Fenta et al. 2014). The use of these root crown phenotyping tools has led to the discovery of multiple
99 phenes (fundamental units of phenotype, York *et al.*, 2013) that impact plant growth in the field.

100 The primary goal of this study was to create a high-throughput system that can extract image-based
101 phenes from the photographed images of plant root crowns using custom hardware and software to
102 optimize the throughput of image acquisition and analysis. Generally, root crowns have been imaged
103 from a single perspective, however legume root crowns are much more asymmetric relative to cereal
104 root crowns. Therefore, imaging from multiple perspectives may better reflect three dimensional
105 aspects of soybean roots. Thus, a system combining a blackout box, internal lighting, image acquisition
106 software, and five consumer cameras was developed and constitutes the Multi-Perspective Imaging
107 Platform (M-PIP). In order to validate extracted phenes from the images, they were compared to
108 manually measured or scored properties. Unlike phenotyping systems that take multiple images using a
109 turntable (Iyer-Pascuzzi et al. 2010; Clark et al. 2011), the images were taken from multiple cameras in
110 order to maximize throughput (no waiting for turntable revolution). Further, the new algorithm for
111 segmentation advanced the state-of-the-art in root phenotyping by making use of hardware acceleration

112 and working on color (RGB) images rather than grayscale. We show that with this combined setup, we
113 can capture and process thousands of images per day.

114 **Methods**

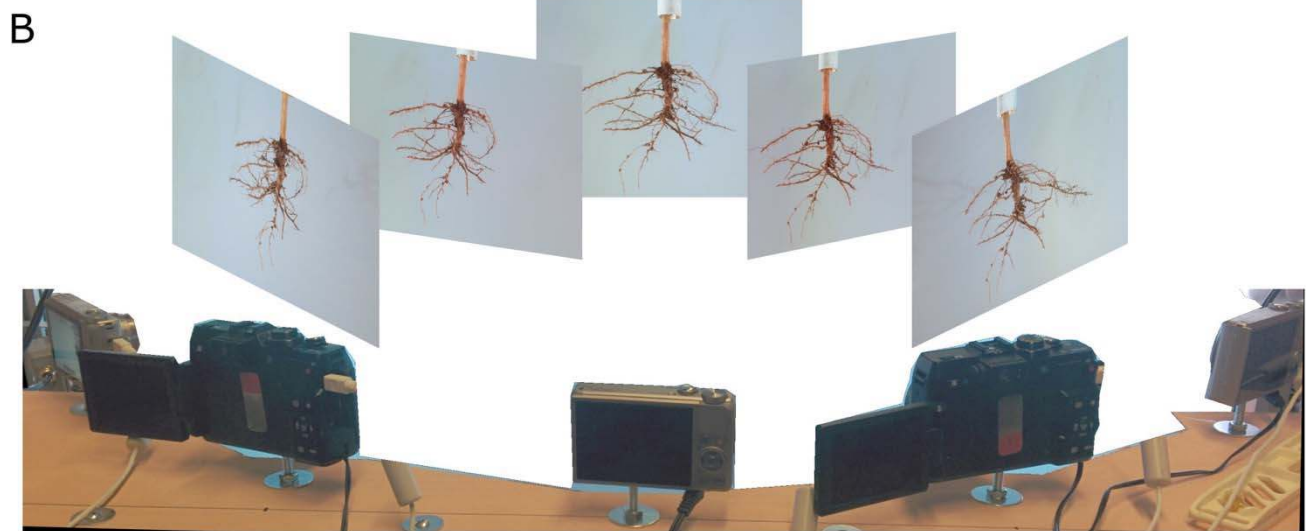
115 Field experiment and root excavation

116 A field experiment including 24 maturity group IV soybean varieties released between 1930 and 2005
117 was conducted in 2016 in Columbia, MO, USA. The soil at the site is a Haymond silt loam (course-
118 silty, mixed, superactive, mesic Dystric Flueventic Eutrudepts) and the field was disked to
119 approximately 0.15 m prior to planting. Soybean were planted at a density of 34 seeds m⁻² on 7 May,
120 2016 in 3.05-m long four-row plots with 0.76 m distance between rows. The varieties were arranged in
121 a randomized complete block design with four replications. Pre-emergence herbicide application and
122 manual weeding were used to control weeds. At beginning seed (R5) (Fehr and Caviness 1977) five
123 plants from one of the middle rows of each plot were cut 10 to 15 cm above the soil surface. To extract
124 the roots from the soil, a circle with a radius of approximately 0.1 m centered on the stem was cut with
125 a shovel and roots were excavated to a depth of 0.2 m. Soil attached to the roots was removed by
126 shaking.

127 Imaging protocol

128 The M-PIP was designed for acquiring images of the same plant root crown from different angles for
129 phene extraction. The M-PIP consists of an imaging box designed for easy operability and
130 transportability. The imaging box measures 137.2 cm (54 inch) wide, 101.6 cm (40 inch) tall, and 121.9

131 cm (48 inch) in depth and consists of a frame of T-slotted aluminum extrusion bars and three sides, a
132 bottom and a top of thin plywood were attached to exclude light and block wind (Figure 1 A). The front
133 side of the box was covered with black cloth that was moved aside to access the interior of the box with
134 the cameras. An opening of 0.6 by 0.4 m was cut into the top of the imaging box and was used to insert
135 the root crowns in the correct position for imaging. To this end, two lids were built to fit the opening in
136 the top of the box and were fitted with a PVC pipe (1" and 0.34 m in length) mounted perpendicular to
137 the plane of the lid and in the center of the lid. Plant stems were placed into the pipe and held in place
138 with a piece of foam pipe insulation when needed, but often the curvature of the stem was sufficient to
139 lock the root in place. This top-loading configuration of root crowns allowed ergonomic and rapid
140 placement of root crowns in a defined location for repeatable imaging. The innovation further allowed
141 high-throughput imaging by use of two lids, such that one root crown was being replaced while another
142 was imaged.



143

144 *Figure 1 A. An imaging station was constructed from T-slotted aluminum extrusion and thin plywood. Internal lighting illuminated a*
145 *suspended root crown against a blue-painted background. Root crowns were affixed to a PVC pipe painted the same as the background*
146 *mounted to a top panel that could be placed over the hole in the back top surface of the imaging box in order to suspend the root crown in*
147 *the focal position of the five cameras. B. Five cameras were placed at equal distances along a 90 degree arc. For clarity, the background*
148 *has been deleted from the photo of the 5 cameras. The five root crown images are the five actual perspectives acquired by each camera.*

149

150 The lid with the attached root crown was placed on the opening in the top of the imaging box, thus
151 positioning the center of the root crown approximately 0.3 m from the plane of the background side.
152 Images were taken from five cameras mounted on a wooden board inside the imaging box. The five

153 cameras were placed along a circular arc equidistant (radius = 0.61 m) from the center of the plant root.
154 The entire arc subtended an angle of 90° at the suspended plant root, and the cameras were placed at
155 equal angles along this arc. When placing the roots in the M-PIP setup box, the perspective having the
156 subjectively maximum spread was placed directly toward the central camera. This was to allow the
157 cameras to capture the entire root structure, to keep consistency among root crowns, and to make sure
158 the roots did not touch background. The cameras in the M-PIP system were configured to acquire
159 images that optimized contrast of the roots with the blue background.

160 The background of the imaging box was painted with light blue to aid with image processing.
161 Additionally, four daylight hued flood lamps (10W, Warmoon, Lightrace Technology Co., Ltd.) were
162 installed to illuminate the root system suspended from the lid. To minimize shadows due to lighting,
163 the illumination was adjusted to achieve diffuse light by the time it reached the background. Initially,
164 aluminum foil was placed on the inside of the black curtain behind the cameras to reflect light and the
165 cameras were placed closer to the background. As part of the optimization process aimed at facilitating
166 image processing, the lights were moved farther away from the background, and the aluminum foil was
167 replaced with a white shower curtain fabric.

168 The M-PIP system was powered by a generator in the field. The power was fed through AC to DC
169 adaptors for each camera instead of batteries, which allowed continual use of the imaging system. All
170 cameras were connected to a USB hub which was in turn connected to a PC. Canon Hacker
171 Development Kit (CHDK) was installed on the SD cards inserted into the cameras. The CHDK was

172 used to programmatically control the camera functions by sending commands from USB using Picture
173 Transfer Protocol (PTP). The commands included changing the optical zoom, aperture, exposure time,
174 ISO speed, capturing images and downloading the images to the PC over the USB connection. A client
175 program was used to send commands to the Canon cameras from the PC. In this implementation for
176 camera control, the cameras used were two Canon G1X cameras and three Canon S110 cameras. The
177 Canon S110 cameras were placed at the middle and at either ends of the wooden board and the two
178 G1X cameras were placed in between the S110 cameras, allowing visual comparison between the
179 images at different angles because these images were obtained by cameras with the same image
180 sensors. The Canon G1X cameras were operated at a focal length of 35 mm and the Canon S110
181 cameras at a focal length of 13.6 mm. The aperture was set to f/8.0 and the ISO speed was set at 800
182 for all cameras, and the exposure time was set to 1/40 seconds for Canon G1X cameras and 1/100
183 seconds for Canon S110 cameras. Once the images were taken, they were downloaded to the PC and
184 segmentation was performed. In total, 480 (24 varieties x 4 replications x 5 roots per plot) soybean root
185 crowns were imaged using the M-PIP. Given the five cameras used, 2400 images in total were
186 acquired.

187 Image segmentation

188 Image segmentation is needed to extract phenes from the plant root pixels located in the image. The
189 images were first manually cropped to only background and the plant root pixels before performing
190 segmentation. This involved cropping the clip or pipe used to hold the plant root at the time of imaging.
191 The segmentation was performed using the Expectation Maximization - Gaussian Mixture Models

192 (EM-GMM) algorithm (Dempster et al. 1977; Bishop 2006), by modeling the pixels as originating from
193 two 3D Gaussian distributions. One Gaussian distribution models the background (blue color) pixels
194 whereas the other distribution models the plant root pixels. The cropped image was passed to the EM-
195 GMM algorithm to generate a segmented image. The largest connected component using flood-fill
196 algorithm from the MATLAB Image Processing toolbox was selected from the segmented image to
197 remove miss-classifications due to noise in the image and saved as the final segmented image.

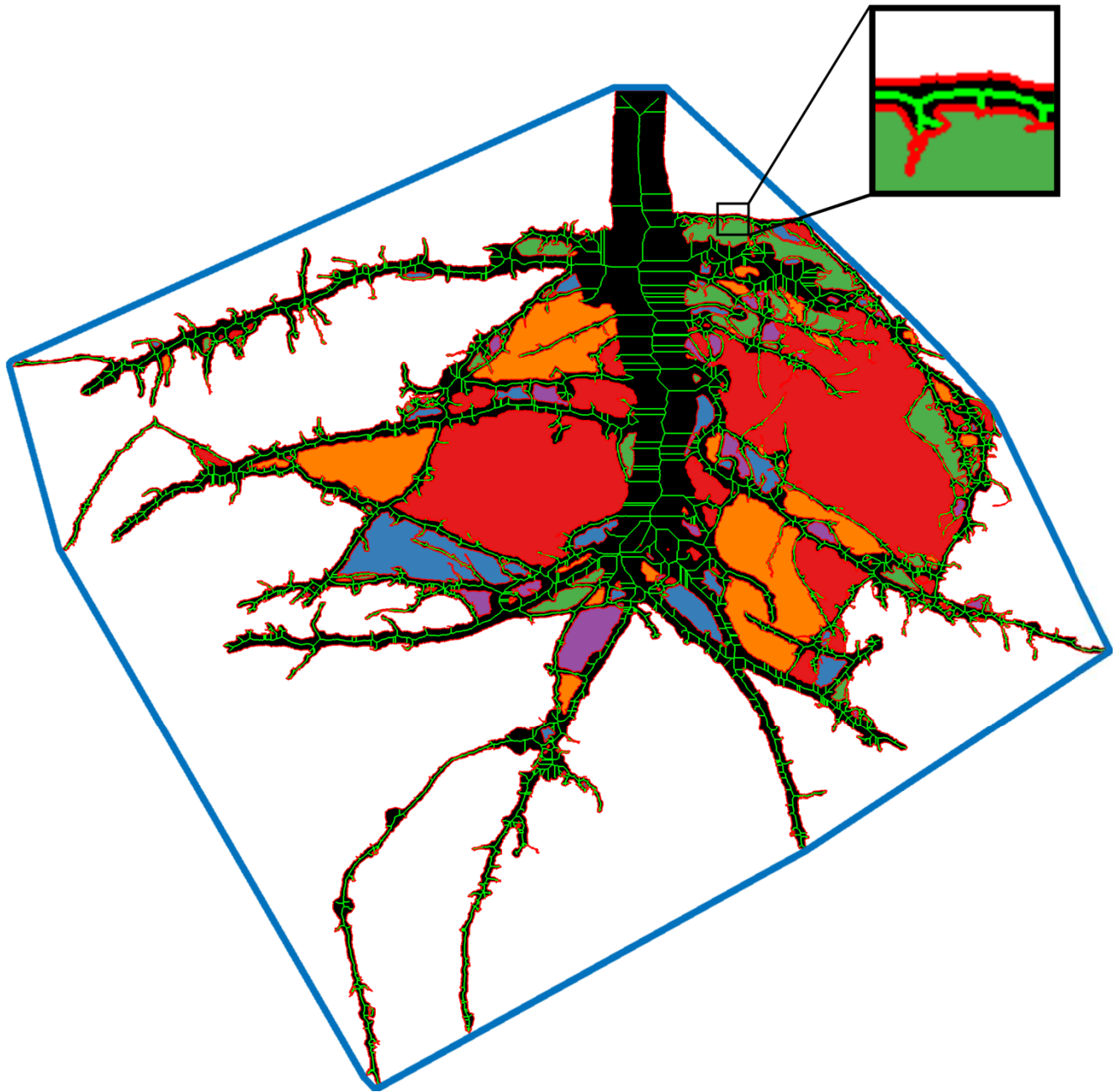
198 The EM-GMM algorithm was implemented in C/C++ and accelerated through the use of NVIDIA
199 Quadro K600 GPU with Compute Capability 3.0. Using our implementation on Intel E3-1271 v3
200 processor having quad-core CPU, which supports for Intel's Advanced Vector Extensions 2.0 (AVX2)
201 and Fused Multiply and Add (FMA) instruction sets, the program takes 25 seconds to segment a 4000 x
202 3000 pixel image. Whereas on NVIDIA Quadro K600 GPU, consisting of 192 CUDA cores, our GPU
203 implementation takes only 10 seconds to segment the same image.

204 The multivariate EM-GMM algorithm was implemented such that the means of the two 3D Gaussian
205 distributions were initialized from the peaks of the histograms of the red, green and blue channels of
206 the image. Since, the images obtained from the cameras had a light blue background, the pixels that had
207 a peak at a greater intensity in all the color channels were initially classified as background pixels. The
208 remaining pixels were taken as the foreground or root pixels. Unlike most of the earlier works
209 (Bucksch et al. 2014; Colombi et al. 2015) based on greyscale thresholding to separate root pixels from
210 background, this EM algorithm auto-tunes the mean and the covariance parameters based on each

211 image so that the likelihood of the pixels is maximized. Also, the algorithm segments an RGB image
212 by estimating the full covariance matrix.

213 Image-based Phene Extraction

214 Phenes were extracted from the segmented images to be used in statistical analysis later. The border
215 pixels from the segmented image were identified and counted for perimeter. The segmented image was
216 also skeletonized and counted to determine total root length. Figure 2 illustrates how the phenes were
217 extracted from the segmented image. Table 1 lists all extracted phenes and their descriptions. For
218 further analysis, the image phenes were aggregated from all perspectives creating four more phenes.
219 The Max. Max. Width is the maximum among the Maximum Widths of the plant root across all
220 perspectives. The Min. Max. Width is the minimum among Maximum Widths of the plant root across
221 all perspectives. The Eccentricity is defined as the ratio of Max. Max. Width to Min. Max. Width. The
222 Max. Max. Width to Avg. Depth Ratio is the ratio of the Maximum Width from all perspectives to the
223 average Depth from all perspectives. This phene is similar to Width-to-Depth Ratio but takes into
224 account all the perspectives.



225

226 *Figure 2 The EM-GMM algorithm generated a binary image with the root crown as a foreground object (black). Image analysis in*
227 *MATLAB generated features such as the convex hull (blue line surrounding crown), the skeleton and length (green lines inside root*
228 *segmented root crown), the perimeter of the root crown (red line along edge of root crown, see insert), and the number and size of*
229 *disconnected components (multi-colored regions surrounded by the root crown edges).*

230 A total of 12 characteristics of the excavated root systems were manually measured or scored as
231 described in Dhanapal et al. (under review), including Overall Complexity, Taproot prominence, Upper
232 Primary Lateral Root Number, Upper Secondary Lateral Root Density, Upper Primary Lateral Root
233 Angle Average, Upper Primary Lateral Angle Range, Lower Primary Lateral Root Number, Lower
234 Secondary Lateral Root Density, Lower Primary Root Angle Average, and Lower Primary Lateral
235 Angle Range, Total Number of Primary Lateral Roots, and Average Lateral Density. Additionally,
236 Stem (1 cm above soil surface) and Tap Root Diameter (at 5 cm below uppermost primary lateral root),
237 and Nodule Size (Average diameter of overall nodules compared to a scale of 1- 5 mm) were measured
238 and Nodule Density was scored (scale from 0 = no nodules to 5 = high Nodule Density).

239 Statistical Analysis

240 Correlation analysis was performed among image phenes and manual phenes to explore the relation of
241 automatically extracted phenes to manual phenes using data from individual root crowns (not averaged
242 for plot). Correlation analysis was also performed for image phenes among different camera
243 perspectives to check the validity of the phenes across perspectives. ANOVA was performed by taking
244 the genotypes and perspectives as factors to test for significant effect sizes using data averaged within
245 each plot. Using this analysis, the phenes that have large effect size for perspective factor may be
246 identified as perspective-sensitive phenes. Finally, heritability calculations and MANOVA analysis for
247 genotype partial effect size was performed on the extracted image phenes from all perspectives and
248 manual phenes. Statistical analyses were performed in *R* (version 3.4). The functions *cor*, *mean* and *sd*
249 were used for computing correlations, means of correlations and standard deviations (SD) of

250 correlations respectively, where mean and standard deviation are given for data averaged within each
251 plot. Similarly, *lm*, *anova* and *manova* were used to make linear models, perform ANOVA and
252 MANOVA, respectively. In this study, linear models were used without any interactions.

253 Some phenes of roots may change as the perspective changes for the same plant root. For example, a
254 root crown may have a smaller width when viewed from one angle compared to another angle (i.e., the
255 root crown is approximately flat). In such a case, the extracted phenes from some perspectives may not
256 correlate well with the manually acquired properties. To address this, the mean of the extracted phenes
257 across all cameras was computed. Phenens were converted from pixel units to physical units before
258 averaging the phenens, using camera sensor sizes and focal lengths.

259 To establish whether genotypes can be separated based on extracted phenotypes, ANOVA was
260 performed on the phenotype data extracted from all five perspectives independently, the average
261 phenotypes derived from the five perspectives, and the manual measures or scores. In total, 480
262 excavated roots were imaged for this study. For each of the 24 genotypes, roots of five plants were
263 imaged from each plot (4 replications) and the plot averages of these five sub-samples were determined
264 for each phene. Broad-sense heritability was calculated based on [2] as:

$$H^2 = \frac{\sigma_g^2}{\sigma_g^2 + \frac{\sigma_e^2}{r}}$$

265 The variables σ_g^2 , σ_e^2 , and r represent the variance of the genotype effect, variance of the environment
266 effect, and the number of replicates (here, 4), respectively. The variances were obtained by fitting a
267 mixed model including genotype as a random effect and replicate as a fixed effect using the *lme4*
268 package.

269 Further, MANOVA was performed for each phene using all perspectives' values as five response
270 variables (Figure 8). The effect sizes in terms of partial eta squared was computed for each image
271 phene using the following equation:

$$272 \quad \eta_{\partial}^2 = \frac{df_g \times F_g}{df_g \times F_g + df_e} \quad (2)$$

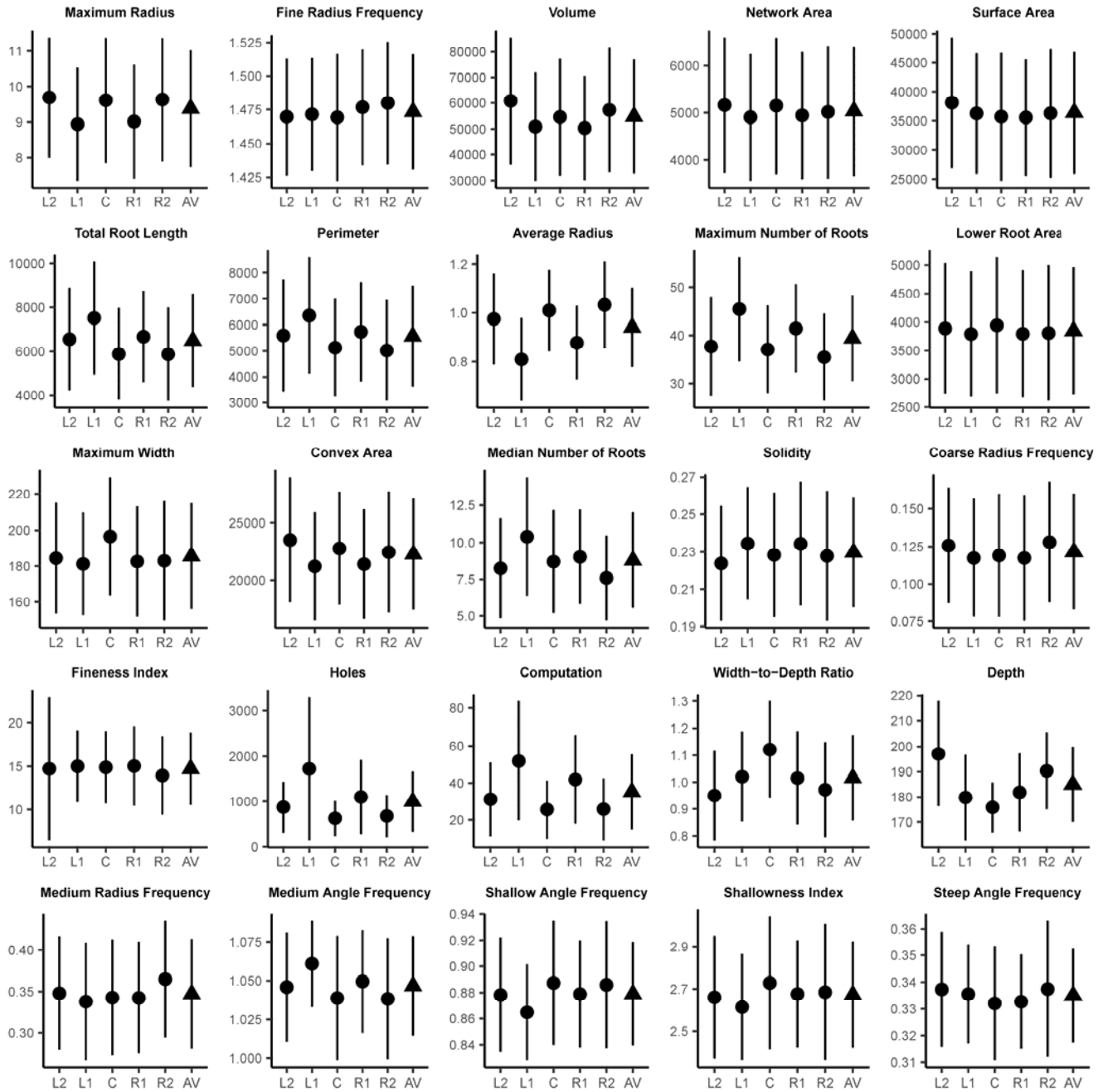
273 where df_g is the degrees of freedom for the genotype factor, F_g is the f-statistic for genotype factor and
274 the df_e is the degree of freedom for residual error.

275 **Results**

276 Twenty-five phenes were determined from image analysis of soybean root crowns excavated from the
277 field (Table 1, Figure 2). The suite of image-based phenes covered various measures of size, length,
278 radius distribution, branchiness, and angles. Phenens were also measured manually for comparison, as
279 described in Dhanapal *et al.* (submitted). In total, 480 root crowns were imaged with five perspectives,
280 yielding 2400 analyzed images.

281 Substantial variation in the population and field replicates existed for all measured phenens (Supp Table
282 1). Comparing means for each phene from each perspective and the averages across perspectives led to
17

283 interesting patterns (Figure 3). As would be expected, the mean of Maximum Width was greatest for
284 the center camera, while the other 4 perspectives were similar. The Depth was greatest for the farthest
285 perspectives (Left 2 and Right 2), but smallest for the central perspective (V pattern). Lower Root Area
286 means were relatively equal across perspectives (flat pattern). For many phenes, the mean of the central
287 camera was most similar to the farther perspectives (W or M patterns).

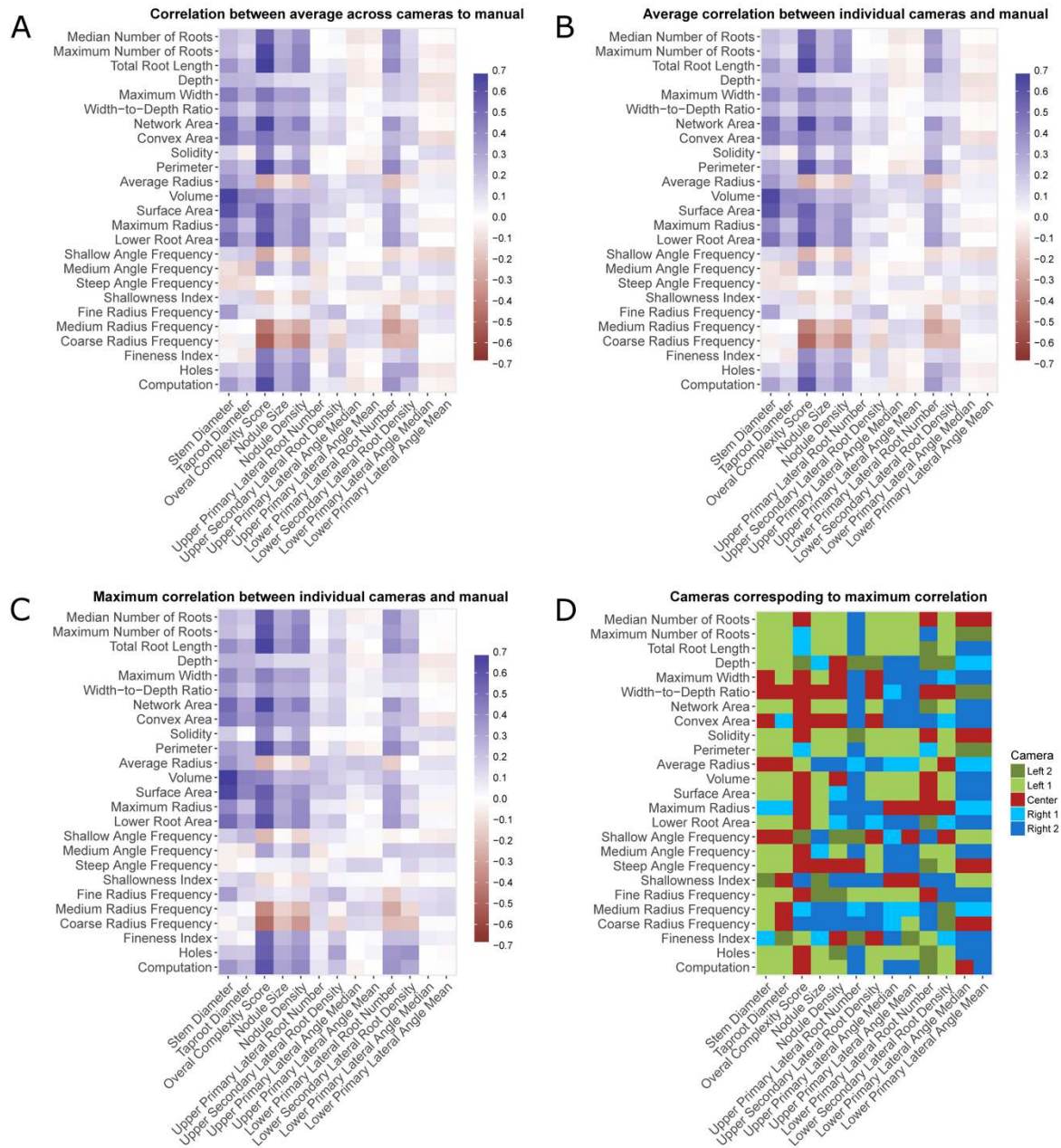


288

289 *Figure 3 Means and standard deviations are given for the 25 image-based phenes, which are defined with respective physical units in*
 290 *Table 1. For each phene, mean + SD is given for each camera perspective, Left 2 (L2), Left 1 (L1), Center (C), Right 1 (R1), and Right 2*
 291 *(R2), all shown with black circles. Black triangles are the average (AV) and SD of each phene across the five perspectives.*

292 Correlation with the manually acquired properties

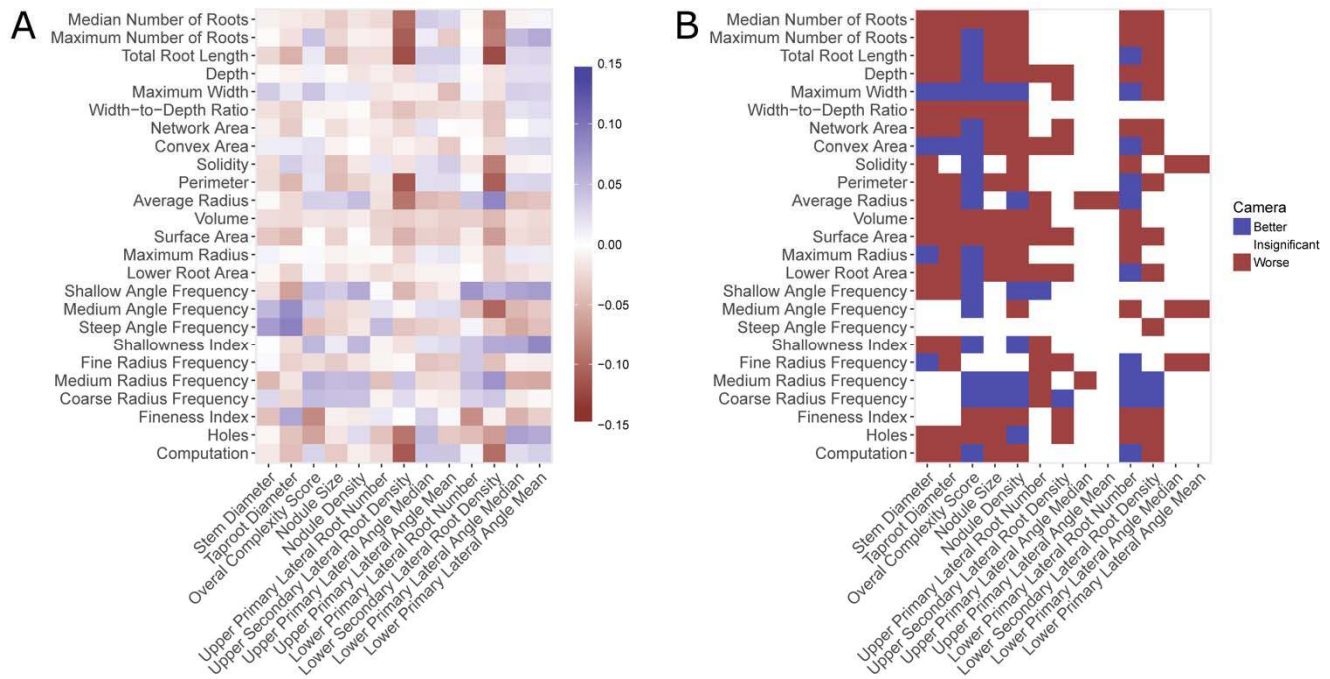
293 For each root, a total of 25 phenes were extracted from each image acquired by each camera.
294 Correlation analysis was performed between image phenes and the manual phenes for each sample.
295 The Pearson correlation coefficients and corresponding P-values were computed for each combination
296 of the different image phenes and manual measures (Figure 4). The correlation analyses were
297 performed (i) for each perspective (camera) separately, and (ii) based on the averages of the phenes
298 obtained from the five perspectives. In addition, an average correlation coefficient was calculated based
299 on the five single-perspective correlation coefficients. The maximum correlation for phenes averaged
300 across the 5 perspectives was 0.67 for the image phene, Total Root Length, and the manual phene,
301 Overall Complexity. The maximum correlation for individual perspectives (single camera) compared to
302 manual measures was found to be 0.65, also for Total Root Length versus Overall Complexity.
303 Similarly, the averaged image phenes across perspectives such as the Network Area, Perimeter, Lower
304 Root Area and Computational Time correlated well with Overall Complexity with correlation
305 coefficients of 0.65, 0.64, 0.61 and 0.63 respectively. The perspectives corresponding to the maximum
306 correlations for each phene combination have no consistent pattern. Overall, there are correlations
307 among image-based and manual phenes, yet it is not clear which should be most relevant as ground
308 truth data.



309

310 *Figure 4 Pearson correlations calculated among digital and manual phenes. A. Correlations of phenes averaged across the five*
 311 *perspectives before correlational analysis with manual phenes. B. Averages of the five correlations from the five perspectives of each*
 312 *digital phene with manual phenes. C. Maximums of the five correlations from the five perspectives of each digital phene with manual*
 313 *phenes D. A map depicting which camera perspectives yielded the maximum correlations given in panel C.*

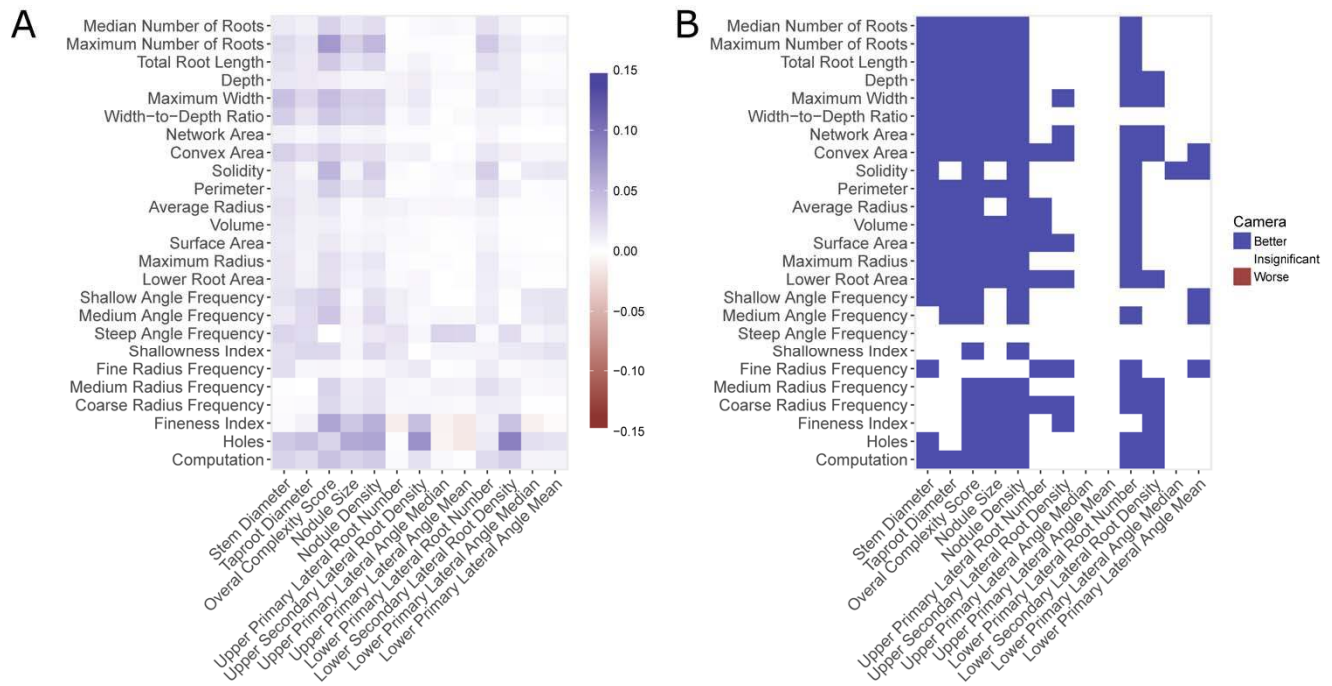
314 In order to test whether averaging multiple perspectives was beneficial for predicting manual
315 measurements, two operations were performed using the correlation tables described above. In Figure
316 5, the maximum correlations derived from individual perspectives were subtracted from the
317 correlations of the average phene across 5 perspectives against manual phenes. In Figure 6, the
318 averages of correlations derived from individual perspectives were subtracted from the correlations of
319 the average phene across 5 perspectives against manual phenes. In both cases, positive numbers
320 indicate the correlations from averaging phenes across 5 perspectives before correlational analysis with
321 manual phenes performed better than the alternative. The averaged phenes did not correlate better than
322 the maximum correlation values across all perspectives for most phene combinations (Figure 5), yet no
323 single perspective had consistently greater correlations than averaging all perspectives (Figure 4).
324 Averaging phenes across 5 perspectives before correlational analysis always performed better than the
325 average correlations across multiple perspectives for phene combinations that are statistically
326 significant (Figure 6). Since no single perspective consistently correlates better to manual phenes, and
327 the best perspective is hard to predict *a priori*, averaging phenes across 5 perspectives before
328 correlational analysis is recommended.



329

330 *Figure 5 A. A heat map of the differences in correlations when the maximums of the five correlations from the five perspectives of each*
 331 *digital phene with manual phenes (Fig 3B) are subtracted from the correlations of phenes averaged across the five perspectives before*
 332 *correlational analysis with manual phenes (Fig 3A). B. Thresholded map demonstrating which differences of correlations indicate*
 333 *greater (better) correlations for averaging phenes across 5 perspectives before correlational analysis (only significant correlations*
 334 *shown).*

335

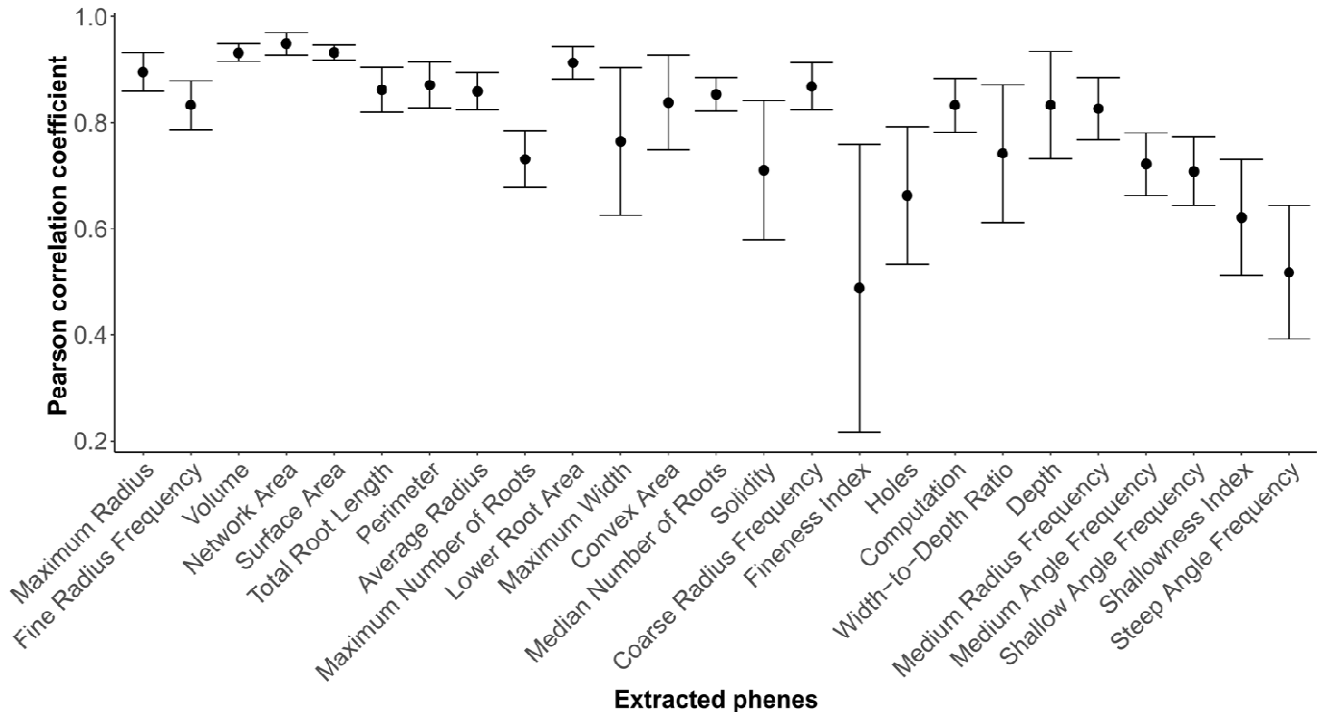


336

337 *Figure 6 A. A heat map of the differences in correlations when the averages of the five correlations from the five perspectives of each*
 338 *digital phene with manual phenes (Fig 3C) are subtracted from the correlations of phenes averaged across the five perspectives before*
 339 *correlational analysis with manual phenes (Fig 3A). B. Thresholded map demonstrating which differences of correlations indicate*
 340 *greater (better) correlations for averaging features across 5 perspectives before correlational analysis (only significant correlations*
 341 *shown).*

342 Inter-perspective correlations

343 The correlations among the five perspectives for each image phene were computed (Figure 7). The
 344 maximum average inter-camera correlation was observed for network area, at 0.949 ± 0.021 (mean \pm SD),
 345 followed by surface area (0.933 ± 0.013) and volume (0.932 ± 0.016). These substantial correlations
 346 indicate that even if the phene values are different from all the perspectives (slopes not equal to 1), the
 347 phene values change predictably across samples. The fineness index has the lowest average inter-
 348 camera correlation of 0.488 ± 0.271 , possibly a function of differential fine root occlusion among
 349 perspectives.



350

351 *Figure 7 Averages and standard deviations for all pairwise correlations among the five perspectives for each image-based feature*
352 *(n=10). Pearson correlations were calculated for all 25 pairs of perspectives before being averaged and the standard deviation*
353 *calculated.*

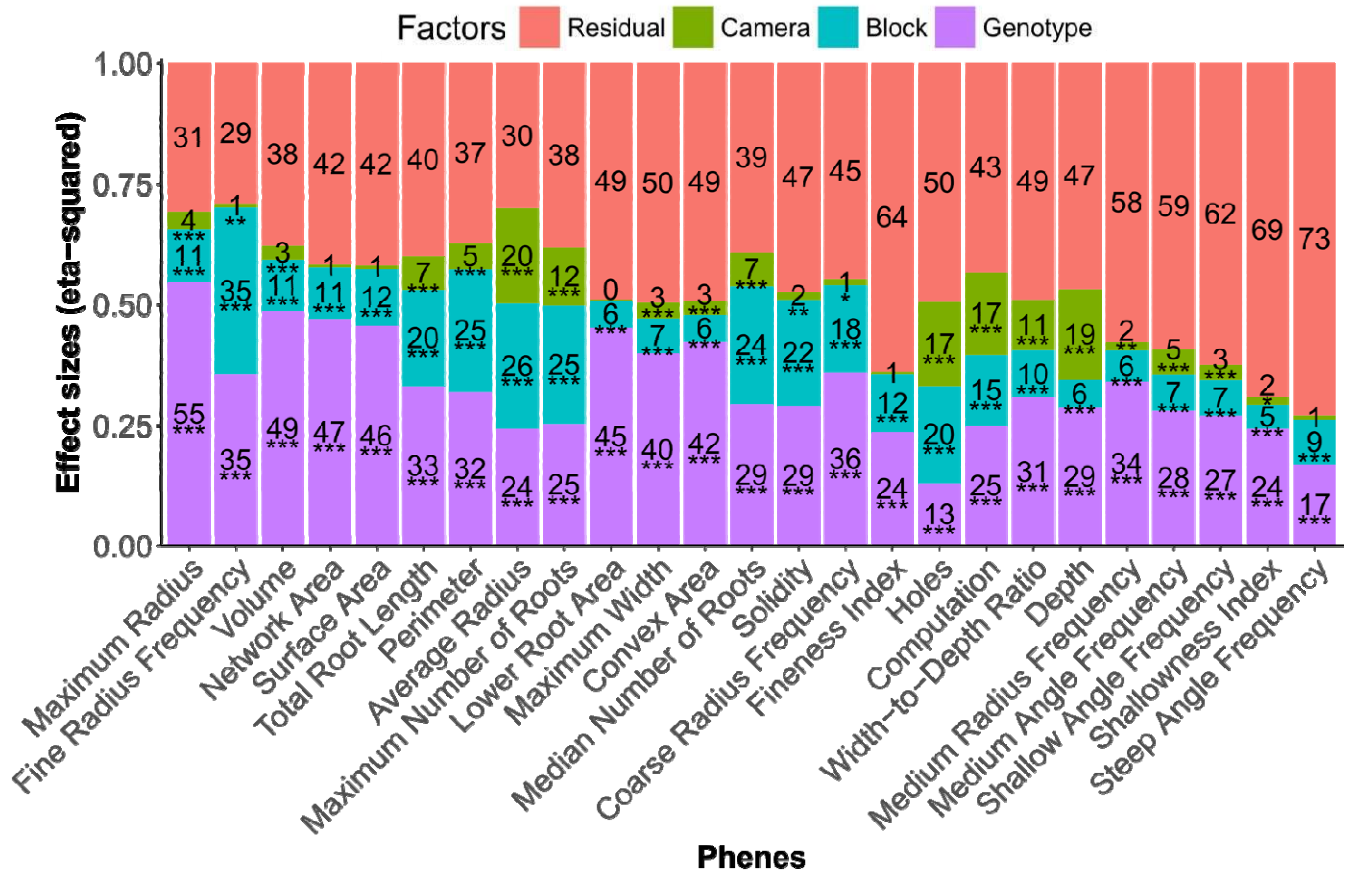
354

355 Analysis of Variance Due to Perspective

356 Since the data was collected from five different perspectives for 24 soybean varieties, ANOVA was
357 performed to partition variation created by the multiple factors in this experiment using eta-squared.

358 The camera perspectives were also considered as a factor as the plant roots were oriented with the
359 plane of maximum spread perpendicular to the central camera. Figure 8 shows the effect sizes of
360 genotype, block in the field, and image perspective, as well as the residual of each image phene.

361 Genotype, block, and perspective effects were significant ($P < 0.001$) for all phenes, except for the
362 perspective effects for Volume, Surface Area, Lower Root Area, Fineness Index and Steep Angle
363 Frequency (ns). The genotype effect size ranged from a low (13%) for Holes to a maximum (55%) for
364 Maximum Radius. Thus, the Maximum Radius was particularly well suited for genotype separation.
365 The phenes with the greatest effect sizes due to different perspectives were Average Radius, Holes,
366 Computation and Depth. For the fineness index factor, the lower effect size associated with perspective
367 agrees well with the large SD of the inter-camera correlations for the same phene in Figure 7.



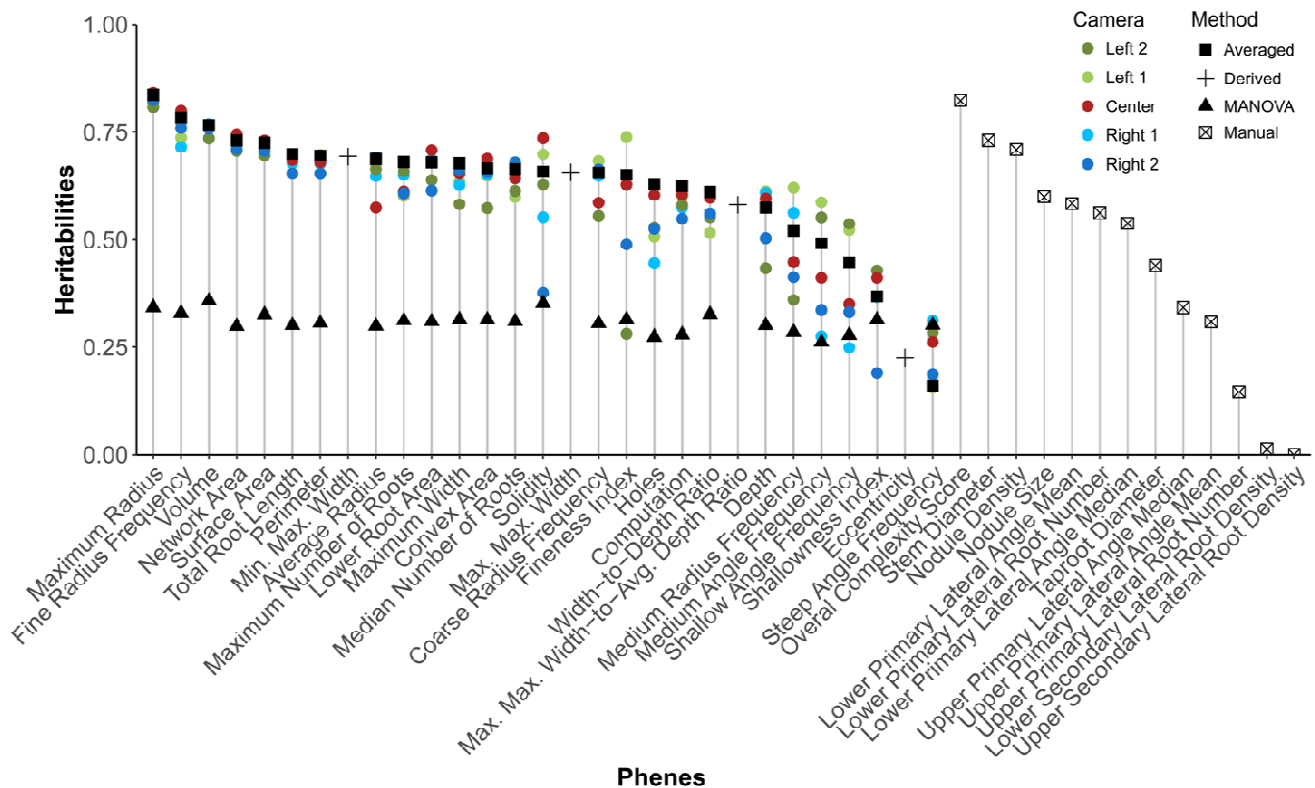
368

369 *Figure 8 Effect sizes of all the factors for each phene extracted from the images. For each effect size, the percentage is shown that*
 370 *contributes to the total variation. Each effect size is marked with the significance of that factor (except for the residual error) based on p-*
 371 *values obtained. '*' was given for p-value < 0.05, '**' for p-value < 0.01 and '***' for p-value < 0.001.*

372 Heritabilities of image-based and manual phenes

373 Broad-sense heritability is an important metric for how suitable a new phene would be for breeding
 374 programs, assuming some phene states have beneficial effects on crop performance. The averaged
 375 phenes across perspectives generally had greater genotype heritability than phenes from individual
 376 perspectives (Figure 9). The greatest heritability for averaged image phenes was Maximum Radius with
 377 a heritability of 0.837 and the greatest heritability for manual phenes was Overall Complexity with

378 heritability of 0.823. For comparing to the results of MANOVA, partial eta-squared was calculated,
 379 which is not directly comparable to heritability, but useful for looking at the differences among image-
 380 based phenes for separating genotypes using raw data from all 5 perspectives directly without
 381 averaging. The largest genotype effect size from MANOVA analysis of image phenes was 0.358 for
 382 Volume. The greatest heritability of derived phenes was observed for Min. Max. Width with the
 383 heritability value of 0.693.



384

385 *Figure 9 The broad-sense heritabilities are plotted for individual camera perspectives (colored circles), using the average across*
 386 *perspectives (black squares), and with manual phenes draw with a black 'x' enclosed in a square. Effect-sizes for MANOVA (black*
 387 *triangles) using all five perspectives for each feature are displayed for comparison.*

388

389 Throughput of root crown imaging, segmentation, and phene extraction

390 The M-PIP system was tested for performance and compared to the existing systems such as *DIRT*
391 (Bucksch et al. 2014) and *REST* (Colombi et al. 2015). The average imaging speeds of the M-PIP
392 system was 1.66 root crowns min⁻¹ whereas the imaging speed given for *REST* system was 1.5 root
393 crowns min⁻¹. Table 2 shows the segmentation time for various algorithms implemented for M-PIP,
394 where the EM algorithm used here with GPU acceleration took 10 seconds to segment color images,
395 while the *DIRT* implementation of Otsu's thresholding took 22 seconds. On average the new feature
396 extraction program, which was implemented in *MATLAB*, required 26 seconds for phene extraction on
397 a PC with an Intel Xeon E3-1271 v3 processor (3.6 GHz) having 4 cores and 16 GB of RAM. An
398 average of 860 seconds was required for phene extraction when the *DIRT* system was run in multi-
399 threaded mode on PC running Ubuntu Linux with Intel Core i5-3440 processor (3.3 GHz) having 4
400 cores and 16 GB RAM.

401 **Discussion**

402 Image acquisition using the Multi-Perspective Imaging Platform (M-PIP) was faster than existing
403 methods with regards to simultaneous imaging of the root crown from multiple perspectives,
404 transferring the image data from each camera to the computer, and the time to place and replace root
405 crowns. The setup box was operated by two persons, one sending commands to cameras to take
406 pictures and the other replacing the plant roots after imaging. The two person team was able to keep up

407 with the root crowns passed by a group of six (three teams with two people each) conducting manual
408 measurements. Since, the setup box was designed to be invariant from external lighting conditions, the
409 images had high contrast of root crown to background, leading to excellent segmentation outputs.

410 The EM algorithm used to segment the color images from the cameras provided more connected root
411 pixels in the segmentation results compared to the segmentation by conventional thresholding
412 algorithms on grayscale images. In this study, a blue-colored background was found to contrast best
413 with roots and allowed the use of multi-dimensional color channel information to better segment roots
414 from the background. This made the color channels in each image to store information for segmenting
415 the images and hence lead to better results. The segmentation and phene extraction for the M-PIP was
416 performed on a PC with an Intel Xeon E3-1271 v3 processor having 4 cores and 16 GB of RAM. The
417 PC has a NVIDIA Quadro K600 GPU with 192 CUDA cores having Compute Capability 3.0 (a
418 performance standard from NVIDIA). Optimization was achieved further by applying hardware
419 acceleration techniques for CPU and GPU, making this program suitable for online segmentation of
420 images. This direct segmentation of the images in the field enables immediate control of image quality
421 and system performance, providing operator peace of mind and the ability to make adjustments if
422 needed.

423 Correlation with the manual phenes

424 The maximum correlation was increased after averaging phenes across the perspectives to 0.67 from
425 the maximum correlation for individual perspectives of 0.65, for the feature combination of the image

426 phene Total Root Length and the manual phene Overall Complexity. The overall complexity is scored
427 manually based on apparent secondary and tertiary roots leading to more or less bushy structures. This
428 means that a majority of the phenes extracted from the images are useful in predicting the complexity
429 of the plant root automatically, and may allow complexity to be deconstructed to more basic properties.
430 While the angle phenes extracted manually did not correlate significantly to the image phenes, the
431 number of lower roots and the stem diameter correlated well. Since manual angles were measured on
432 primary laterals whereas image-based angles were calculated for every pixel in the skeleton, including
433 the taproot, secondary roots, and tertiary roots, the manual and image-based measures are
434 fundamentally different. Additionally, angles may not be same as seen from various imaging
435 perspectives and manual root angles were measured using a protractor in a perspective where the roots
436 are spread widely, similar to the central camera. Additionally, occlusion of roots by other roots when
437 viewed from particular perspectives may have contributed to the lack of significant correlations
438 between manually measured angles and imaged based phene. The greatest negative correlations can be
439 observed with the number of medium and coarse roots in a root crown with the overall complexity.
440 This indicates that investment into large radii roots may decrease length and branching, leading to a
441 decrease in overall complexity. The manual phenes Nodule Size and Nodule Density had minimal
442 effect on overall complexity. Both manual and image-based measures may have relevance for
443 agronomic performance, a focus of future work.

444 The camera perspectives of phenes that led to maximum correlations with the manual phenes were
445 distributed with no obvious pattern (Fig. 3D), indicating that no single perspective consistently

446 performed better than any other perspective. Although the average phenes across all perspectives did
447 not perform as well as the maximum correlations selected from among the five perspectives (Fig. 4),
448 the best performing perspective could not be predicted *a priori*. Hence, if the phenes from all the
449 perspectives were averaged, an overall improvement in the correlation may be observed because the
450 average of these phenes reduces the effect of the outliers that were present when the root crown was
451 imaged from multiple perspectives. The average of the phenes from all the perspectives always out-
452 performed the average correlations across all the perspectives. Therefore, averaging features across all
453 five perspectives before analysis is recommended.

454 Inter-camera correlations

455 The image phenes from various perspectives generally correlated well, except for a few phenes that
456 significantly vary among perspectives. For example, finer roots easily can be blocked by coarse roots
457 which may lead to a large variance in their numbers from different perspectives. This is shown in the
458 Figure 7, where Fineness Index and holes had greater SD in correlations across all perspectives. Also,
459 the orientation of the root either increases or decreases as a function of perspective. This may lead to
460 misidentification of some shallow and medium angle roots as steep angle roots in some perspectives.
461 While the SD for correlations of Maximum Width was reasonable because the phene varies with the
462 change in perspective, a similar SD for correlations of Depth was curious. However, this may be
463 attributed to the Depth of some roots exceeding the dimensions of the image in some perspectives
464 which may be caused by non-precise alignment angles at which the cameras were mounted. Greater SD
465 was also observed for phenes such as Convex Area and Solidity, which is reasonable as Maximum

466 Width also had greater SD as perspective changed. The phenes with large inter-camera correlations and
467 small SD such as network area, volume, and surface area etc. may be considered perspective
468 insensitive. Hence, these phenes may be particularly well-suited and reliable when the root crowns are
469 imaged from a single perspective. Greater SD for a phene correlation may imply that the perspectives
470 may hold more information about the root crown such as the information needed for genotype
471 separability.

472 Factor separability of image-based phenes

473 Among image-based phenes, the absolute and relative effect sizes of the genotype, block, perspective,
474 and residual error vary greatly (Figure 8). The phenes Average Radius, Holes, Computation and Depth
475 have relatively larger perspective effect sizes. This was due to the larger width roots occluding the finer
476 roots. As the perspectives changed the Average Radius and Holes changed and hence the
477 Computational time also changed. Here, the Computational time may be approximately considered as
478 proportional to the complexity of the root crown. When the perspective is changed the root may be
479 recorded as smaller or larger size or having small or large number of Holes. If the root crown is large in
480 size and the larger number of Holes, the Computational time increases. On the other hand, if the root
481 crown is large in size and bushy such that the Holes are not visible, the Computational time decreases.
482 This explains the similar perspective effect size of Computational time with Holes and the smaller
483 genotype effect size of this phene, even though this phene correlates well with the manual phene
484 Overall Complexity.

485 Frequency-based phenes had smaller effect sizes for the perspectives factor. This was attributed to the
486 roots contain a majority of finer roots than coarse roots, thus counting of coarse roots from multiple
487 perspectives may lead to similar values, thereby decreasing the effect size and significance. In case of
488 Fine and Medium Radius Frequencies, the effects of occlusion, made the phenes less significant. In the
489 Angle Frequencies, change in the perspectives also changes the angle of the roots. This substantial
490 dependency on the change in perspective coupled with the problems due to occlusion resulted in a
491 smaller effect size of Frequency phenes for the perspective factor.

492 The genotype factor generally had a larger effect than perspective and block. Interestingly, the phenes
493 that were most susceptible to change in perspective were not well-suited to separate genotypes. On the
494 other hand, many of the phenes that were susceptible to perspective yielded greater partial effect sizes
495 when performing MANOVA using phenes from all the perspectives to test for genotype separability
496 (Figure 9).

497 Heritabilities of image-based and manual phenes

498 Heritability and MANOVA results revealed that the image phene maximum radius had a greater
499 heritability than the manually scored Overall Complexity (Figure 9). For genotype separation, the
500 averaged phenes from all camera perspectives generally perform better than the phenes from individual
501 perspectives. This shows that imaging roots from multiple perspectives may provide information which
502 may otherwise be lost or limited due to occlusion of roots and changes in angle based on perspective.
503 To examine the influence of multiple perspectives for genotype separability, MANOVA was performed

504 by taking the phene values from across all the perspectives. The Volume and Solidity phenes had the
505 greatest MANOVA partial effect-sizes compared to the remaining phenes. Interestingly, the phenes
506 having larger effect-sizes for the perspective factor did not have higher MANOVA partial effect size
507 (from Figure 9). This indicates that effect-sizes in perspective factors for these phenes did not contain
508 information for genotype separability. On the other hand, the phenes Volume and Solidity have larger
509 effect-sizes in MANOVA analysis than using phenes from single perspectives for heritability. This
510 shows that including each perspective in the analysis for these phenes can increase genotype
511 separability using MANOVA. The phenes for the Angle Frequencies had smaller heritabilities and
512 MANOVA partial effect sizes. This may be attributed to the change in orientation of the roots as the
513 perspective changed. Also, both Volume and Solidity are susceptible to occlusion, likely contributing
514 to smaller partial effect-sizes in MANOVA analysis. In the aggregated features combined from the
515 phenes from all the perspectives, the phene Min. Max. Width had a greater heritability than the
516 Maximum Width, and that of the phene Max. Max. Width had smaller heritability. While these
517 aggregated phenes have very similar heritabilities, more studies are needed to conclude that these
518 aggregated phenes can be used reliably in root crown phenotyping.

519 The similarity of heritabilities of image phenes and those of manual phenes indicates that the image
520 phenes can be used reliably. The image phenes can be investigated further to better understand their
521 role or importance for plant growth and performance in different environments. The phenes with the
522 greatest heritabilities may be the most useful for breeding, but more needs to be known about their
523 relation to crop performance.

524 **Conclusions**

525 The Multi-Perspective Imaging Platform described here is capable of imaging hundreds of root crowns
526 a day from five perspectives. A reliable segmentation algorithm which can efficiently retrieve the root
527 structure from color images was implemented. The segmentation program utilized hardware
528 acceleration leveraging CPU and GPU resources present on the PC to achieve faster segmentation rates
529 without compromising on the quality of the segmentation process. A variety of root phenes were
530 extracted, some are based on the size and appearance of the plant root, while other phenes were
531 intended to extract hidden structures or additional information about the roots. Image acquisition in the
532 field was faster than documented for the REST platform, and image analysis was faster than DIRT but
533 slower than REST (which used greyscale thresholding). Finally, using phenes across perspectives
534 allowed both greater correlations to manual phenes and greater heritabilities relative to only using
535 individual perspectives.

536 Future improvements in image phene extraction include implementation of new phenes such as root
537 angles from each root class and novel ways of merging phenes from multiple perspectives instead of
538 using the mean across all camera perspectives. Such advances may result in greater precision when
539 used for genetic mapping and thus more reliable genetic markers for breeding purposes. Furthermore,
540 more integration of hardware and software specifically for root crown phenotyping has potential to
541 greatly increase throughput and reliability.

542 The M-PIP facilitates rapid, quantitative assessment of root phenes and can be used in physiological
543 experiments to link root phenotypes to measures of crop performance such as grain yield, nutrient
544 content, and shoot mass. Likewise, the phenes can be mapped to genetic regions using QTL analysis
545 and GWAS to enable marker assisted breeding for root phenes. As such, the M-PIP system can
546 facilitate the inclusion of specific root phenes as targets for breeding programs to aid in the
547 development of more productive, stress tolerant crops and reduce environmental impact due to nutrient
548 loss from agricultural ecosystems.

549 **List of Abbreviations**

550 ANOVA – Analysis of Variance

551 CHDK – Canon Hacker Development Kit

552 EM – Expectation Maximization

553 M-PIP – Multi-Perspective Imaging Platform

554 MANOVA – Multi-variate Analysis of Variance

555 PTP – Picture Transfer Protocol

556 RCBD – Randomized Complete Block Design

557 RSA – Root System Architecture

558 **Declarations**

37

559 **Availability of data and materials**

560 Raw images and/or segmented masks are available upon request. Software code is available on github
561 (DOI: 10.5281/zenodo.1213805 | website: <https://github.com/GatorSense/MPIP>).

562 **Competing Interests**

563 The authors declare no competing interests.

564 **Restrictions or Required Licenses**

565 No restrictions on this research are known under local or national laws.

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569 **Authors' contributions**

570 AS wrote the software, imaged root crowns, conducted data analysis, and wrote the manuscript. LY
571 provided input to software, built the current imaging platform, imaged root crowns, gave input to data
572 analysis, and wrote the manuscript. HA managed the field experiments, helped build the platform,
573 measured manual phenes, helped analyze data, and helped write the manuscript. FF and AZ conceived
574 of the project, directed the design of the imaging platform, directed software design, gave input to data
575 analysis, and wrote the manuscript.

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579

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- 679

680 Tables

681 Table
682
1. Features of root systems extracted from the segmented images with descriptions.

Features extracted	Description	
Median and maximum number of roots	Horizontal line scans are performed from left to right in each row through the segmented image. When pixels change from background to root, then one root is counted. The number of roots are recorded from each row of the segmented image and the median and maximum number of roots was determined from these values.	
Total root length (mm)	It was determined by counting the total number of pixels in the skeletonized image.	688
Depth, maximum width (mm) and width-to-depth ratio	The values for both depth and maximum width are obtained from the dimensions of the segmented image containing the plant root. The width-to-depth ratio is the ratio of maximum width to the depth of the image.	
Network area (mm²), convex area (mm²) and solidity	Network area is the total number of pixels in the segmented image. The convex hull of a geometric shape is minimal sized convex polygon that can contain the shape. The ratio of network area and the convex area was noted as the solidity.	692 693 694
Perimeter (mm)	Perimeter is the count of total number of pixels in the perimeter image.	
Average and maximum radius (mm)	For each pixel on the medial axis of the segmented image, the distance to the nearest non-root pixel was computed and was noted as the radius at that pixel. A list of radii was obtained from the medial axis pixels and determine the average and maximum radii.	698 697 698
Volume (mm³) and surface area (mm²)	Using the radii determined earlier, the sum of all cross-sectional areas across all the medial axis pixels was noted as volume and the sum of the perimeter across all the medial axis pixels was noted as surface area.	699
Lower root area (mm²)	The lower root area is the area of the segmented image pixels that are located below the location of the medial axis pixel, which has the maximum radius.	702 703
Holes	Holes are the disconnected background components that were counted by inverting the segmented image and performing connected component analysis.	704
Fine Radius Freq., Medium Radius Freq., Coarse Radius Freq.	From the skeletal image, the medial axis pixels are grouped into fine, medium or coarse roots based on the radius values at the pixels.	705 707
Fineness Index	The ratio of the number of fine medial axis pixels to the number of coarse medial axis pixels.	
Shallow Angle Freq., Medium Angle Freq., Steep Angle Freq.	Given the skeletal image, for every pixel in the medial axis, the locations of the medial axis pixels in a 20x20 pixel locality were identified and the orientation of these pixels in the locality was determined. This orientation was noted for every medial axis pixel. Given these orientations the pixels were grouped as steep, medium, or shallow.	709 710
Shalowness Index	The ratio of the number of medial axis pixels having shallow angles to the number of medial axis pixels having steep angles.	
Computational time (seconds)	The time taken in seconds to extract all features in an image.	713 714

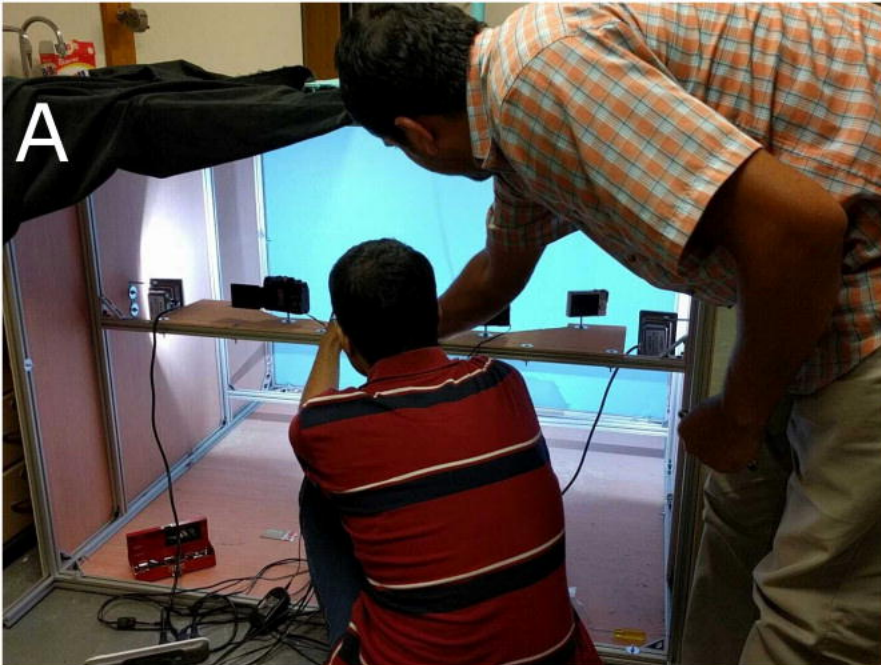
Table
2. Average

715 time required for the segmentation of all 2400 images across platforms. RVM and EM calculations

716 were on a Intel Xeon E3-1271 v3 processor (3.6 GHz) having 4 cores and 16 GB of RAM, REST was
717 reported in the original paper, and the DIRT implementation was run on an Intel Core i5-3440
718 processor (3.3 GHz) having 4 cores and 16 GB RAM.

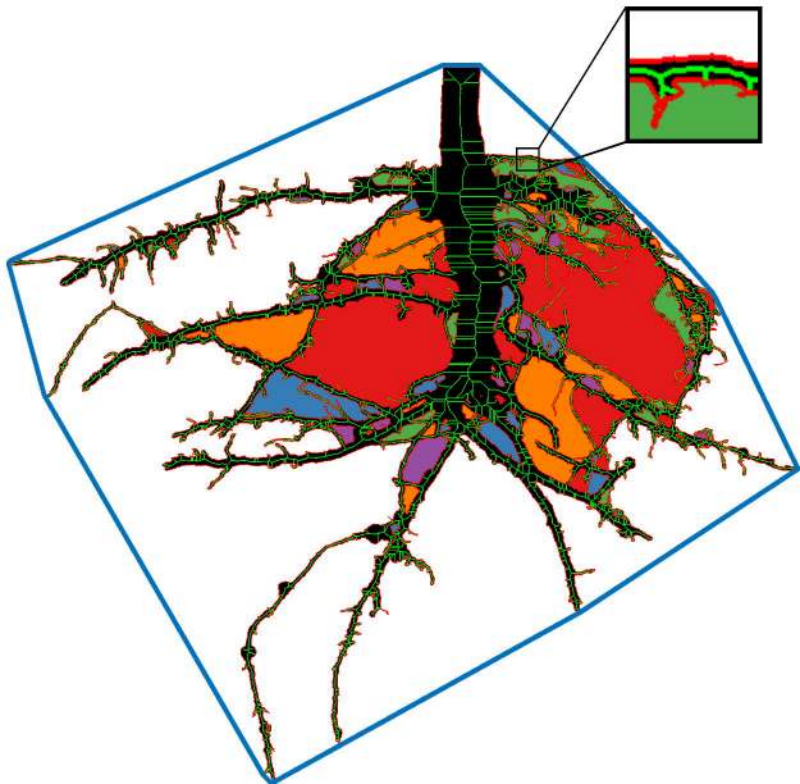
719

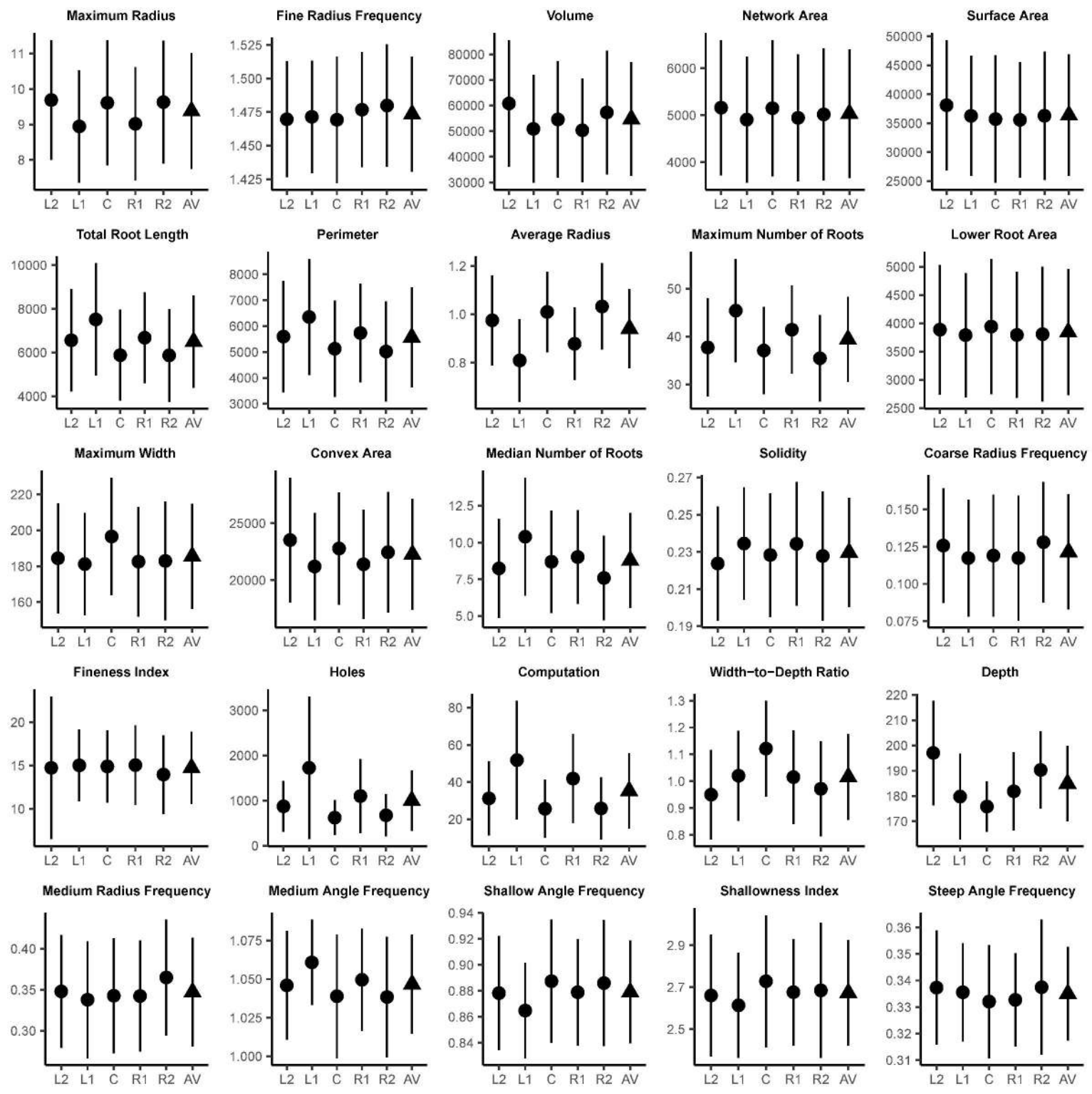
Segmentation Method	Average segmentation time (seconds)
RVM implementation in <i>MATLAB</i>	90
EM implementation in <i>MATLAB</i>	50
EM implementation in C++ with CPU acceleration	25
EM implementation in C++ with GPU acceleration	10
Image thresholding with trait extraction in REST system	6
DIRT implementation of image thresholding	22

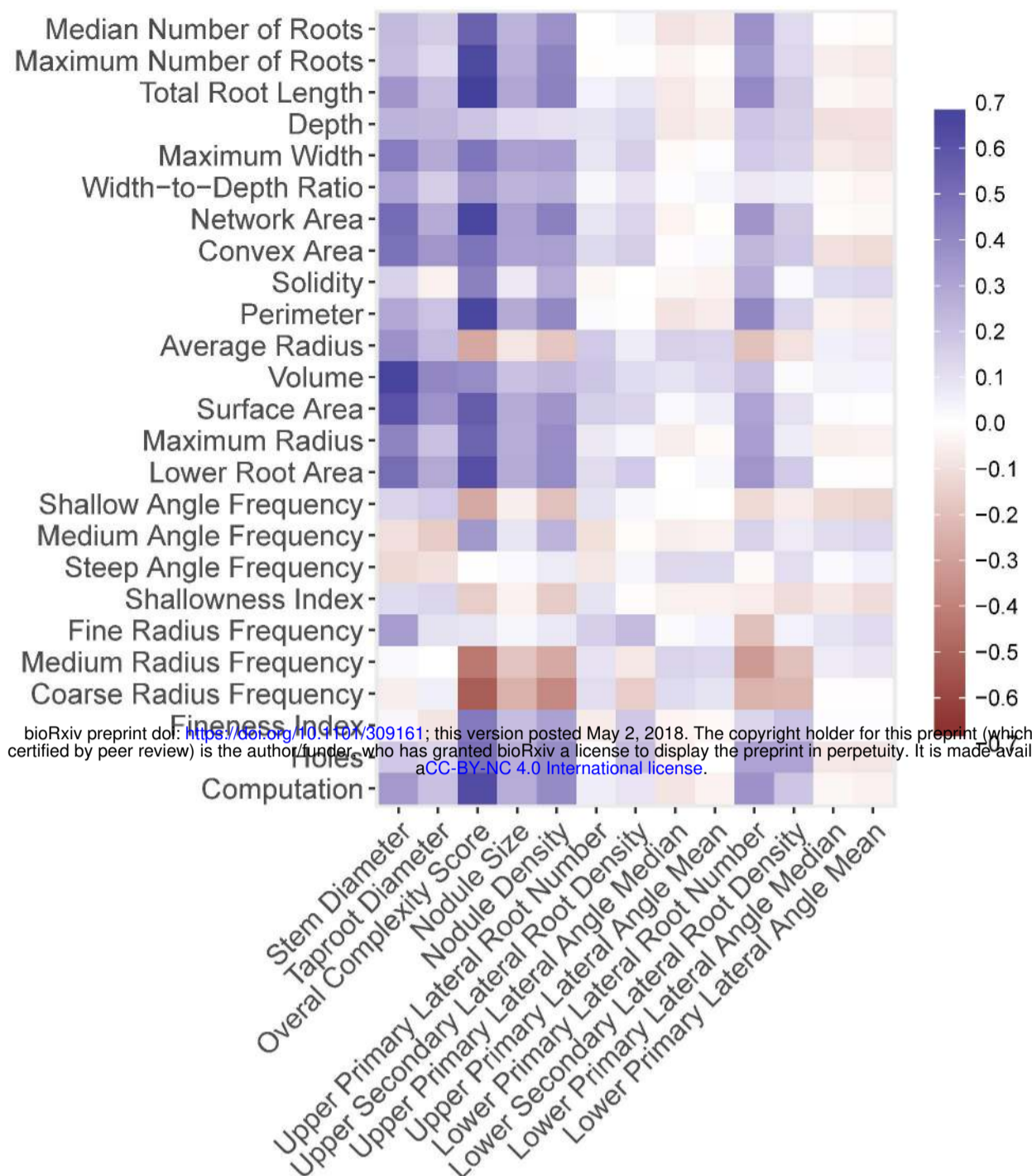
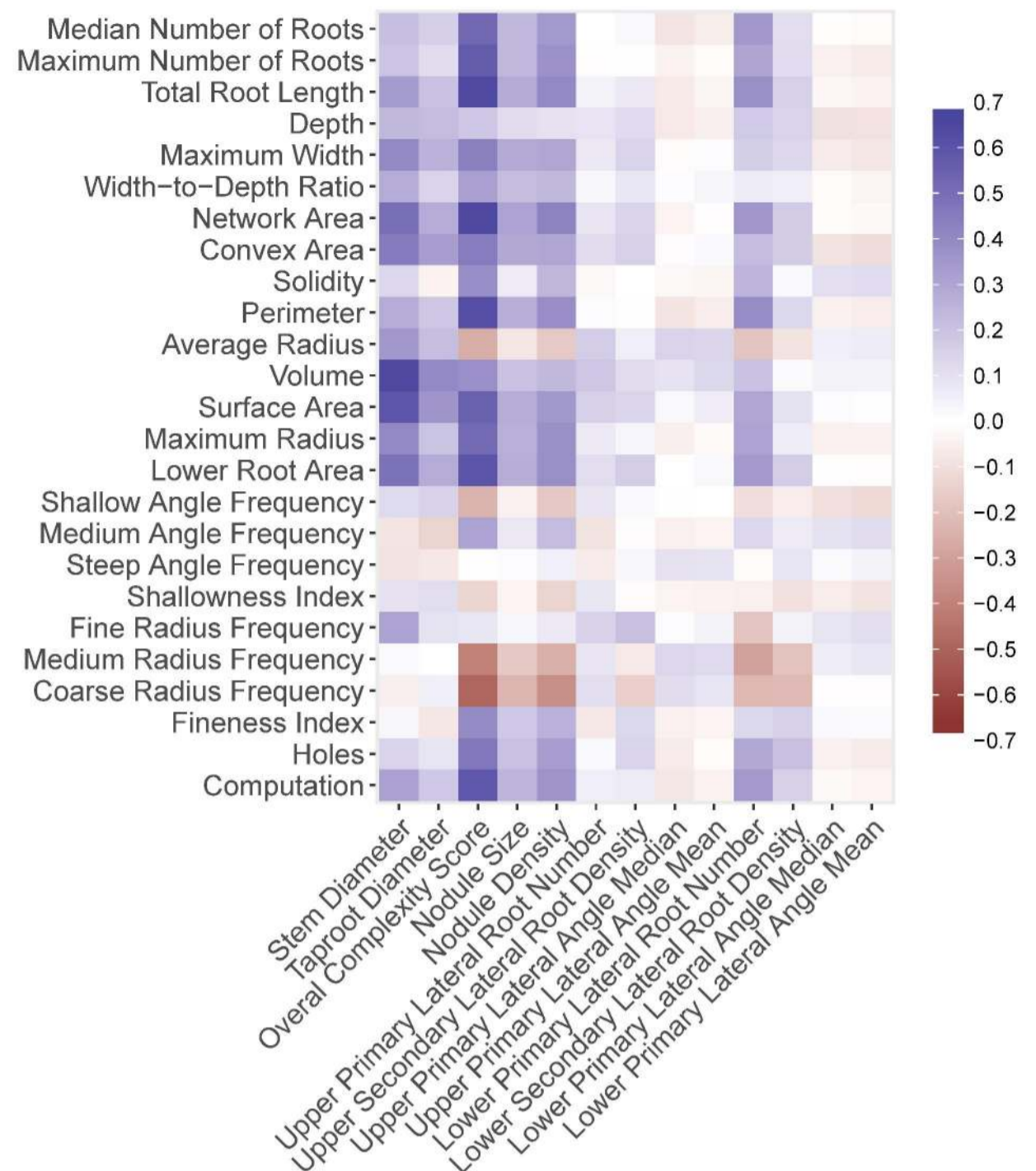
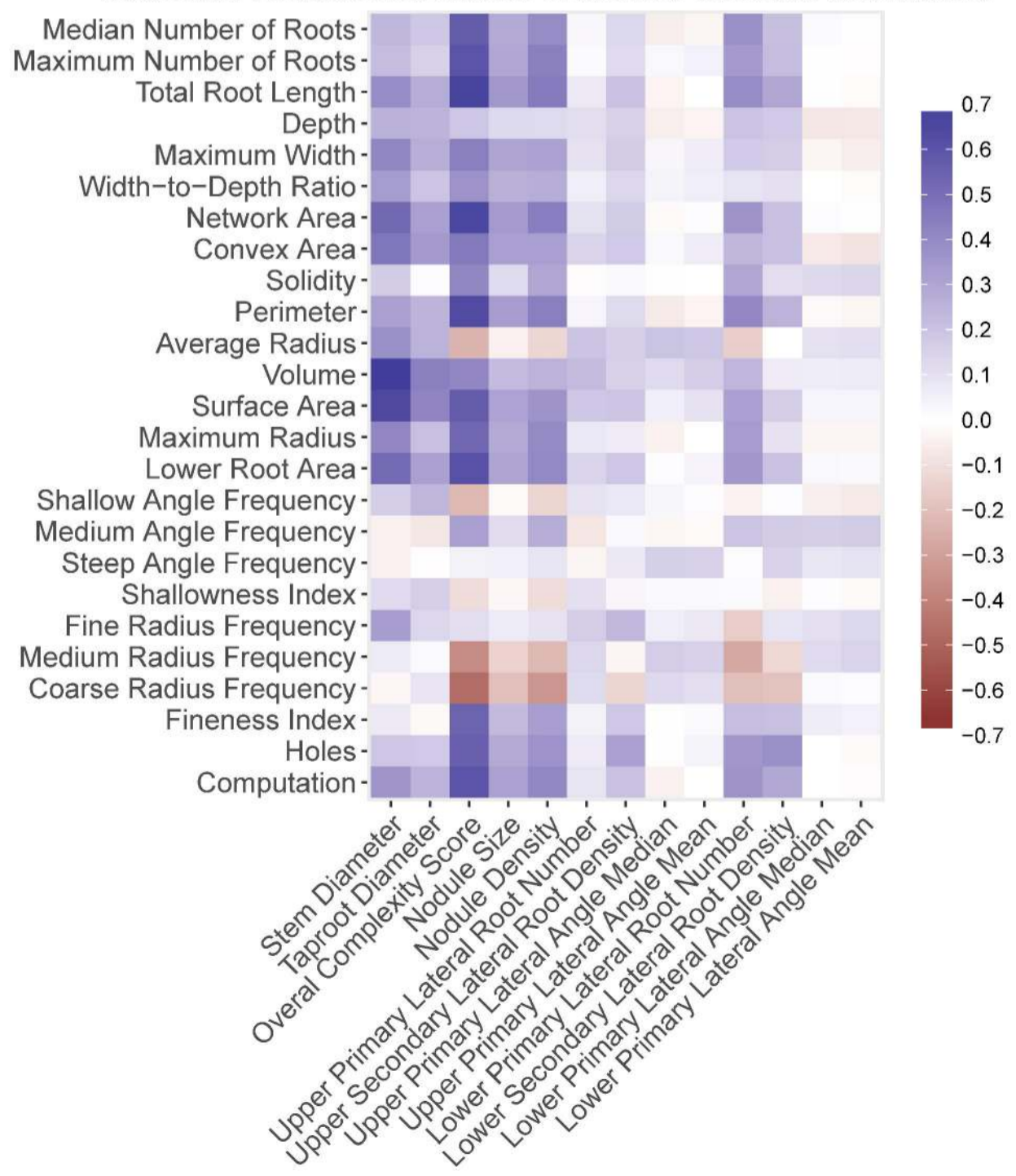
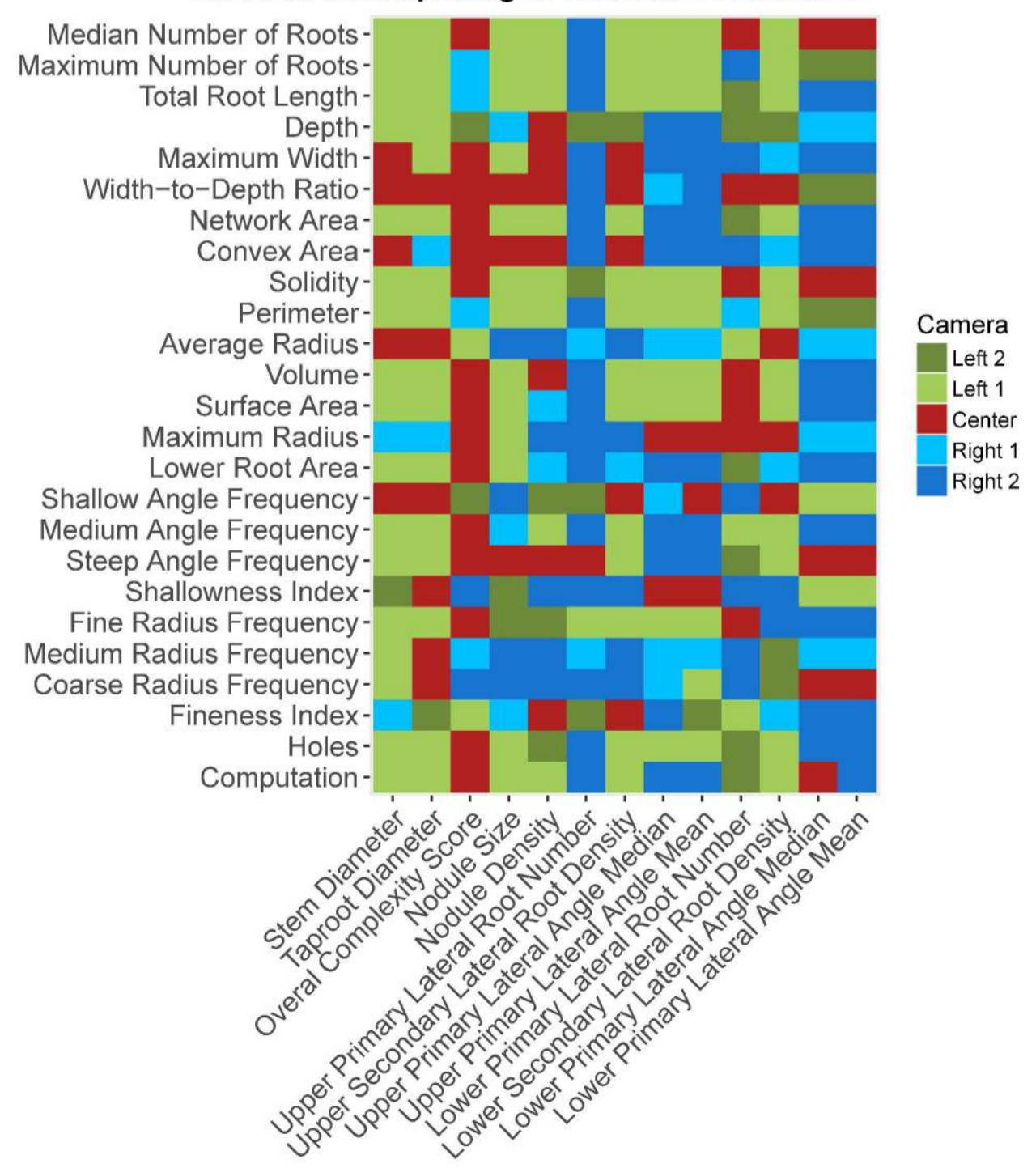


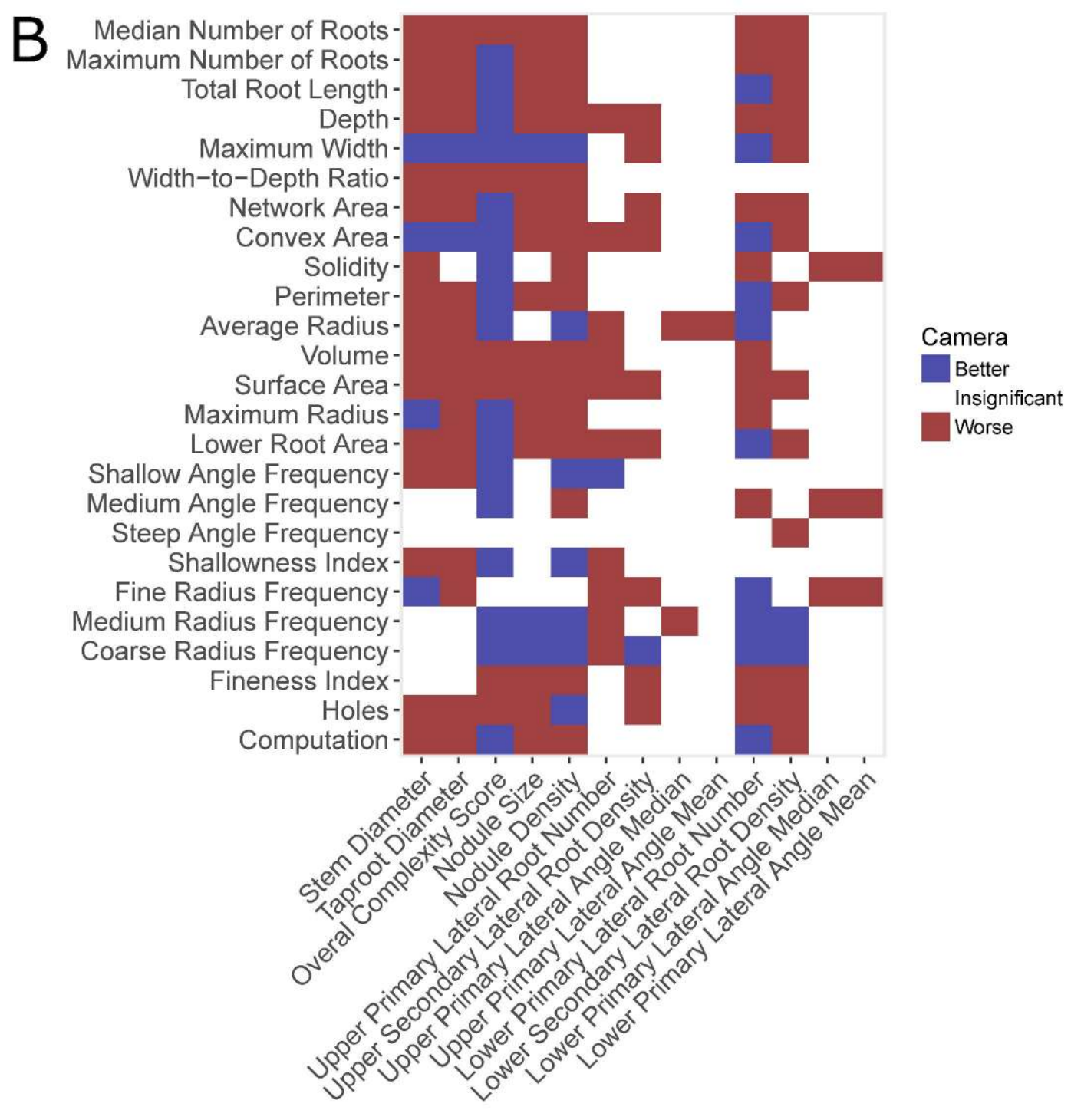
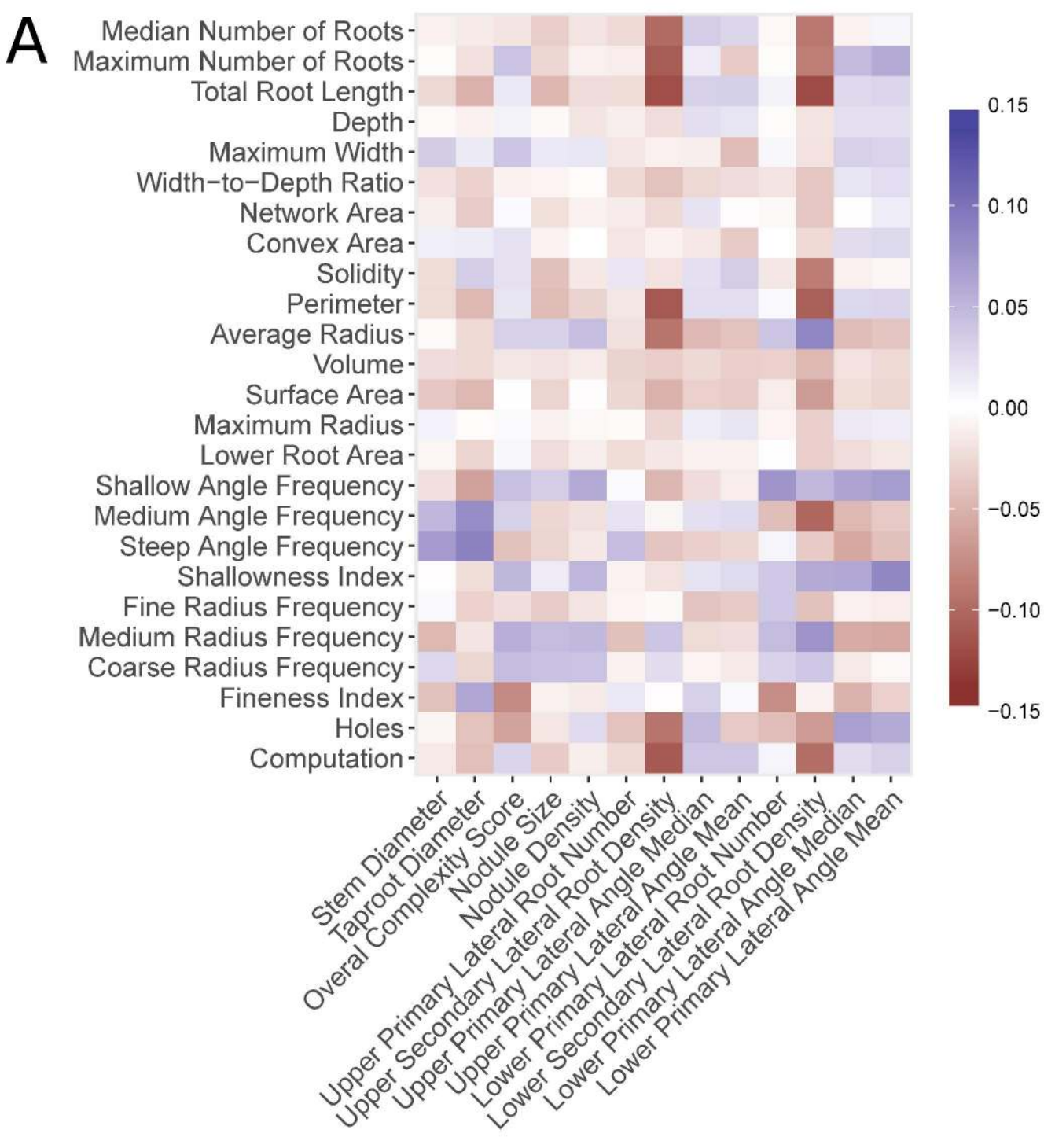
B



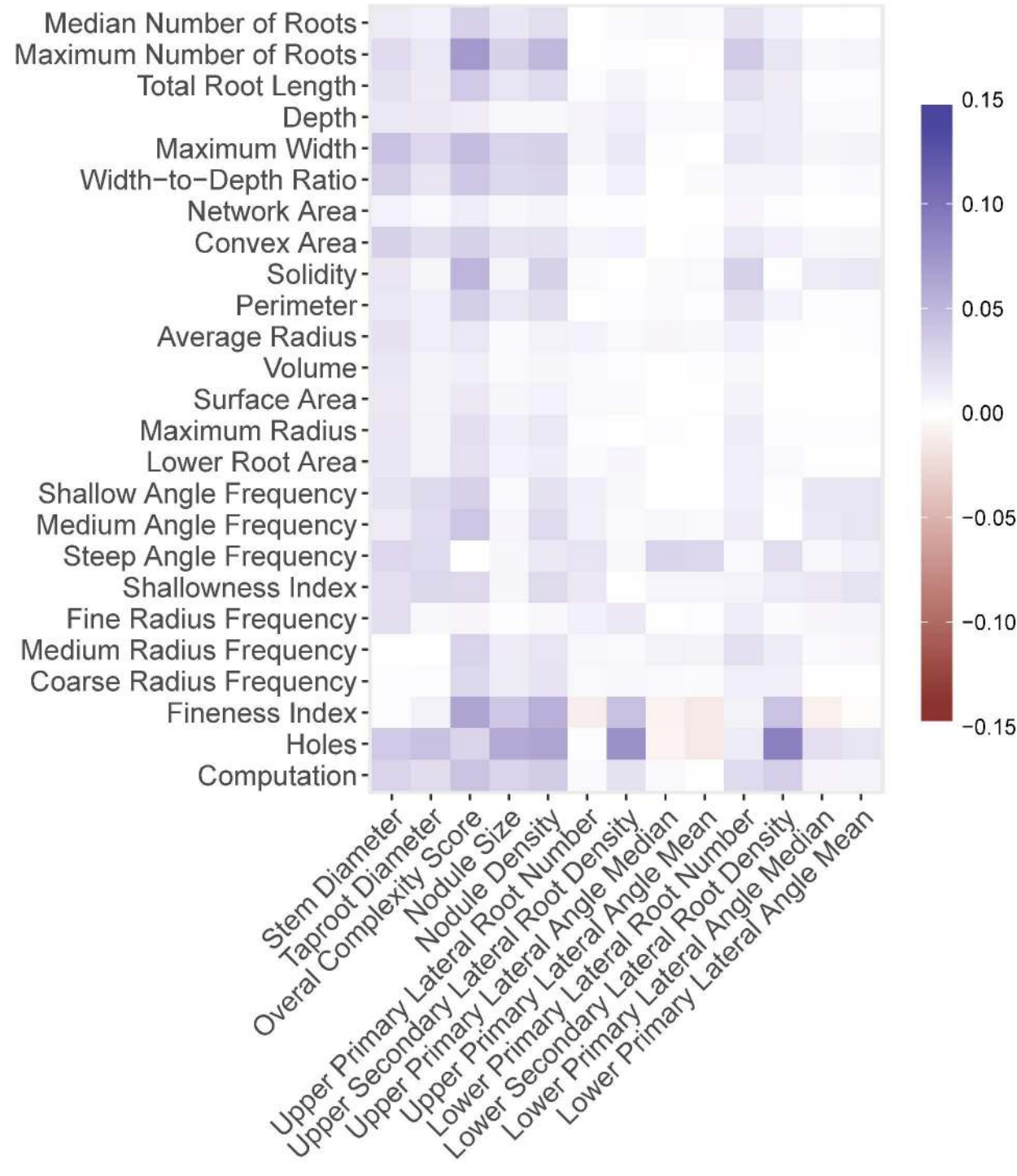




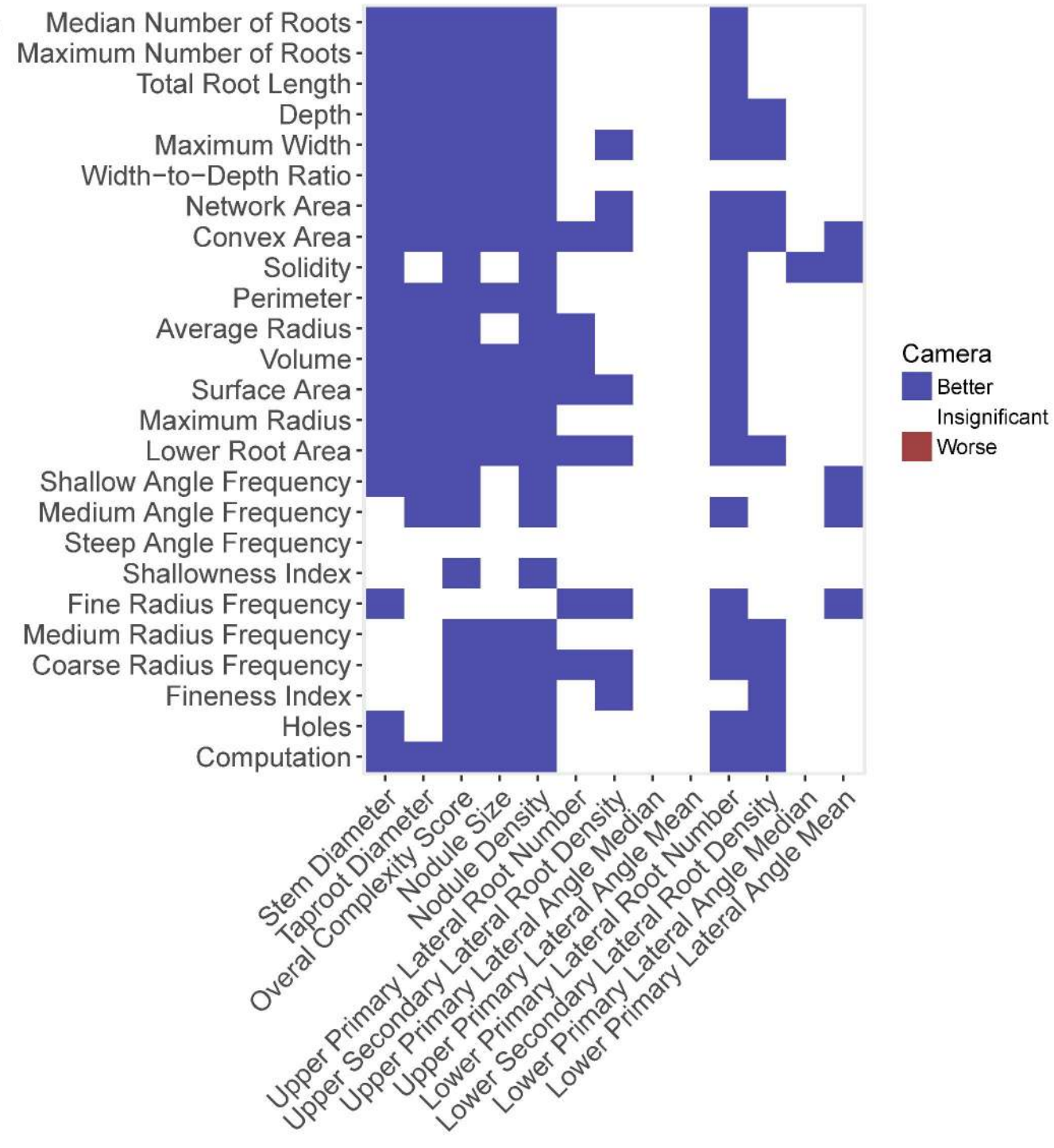
Correlation between average across cameras to manual**B****Average correlation between individual cameras and manual****C****Maximum correlation between individual cameras and manual****D****Cameras corresponding to maximum correlation**

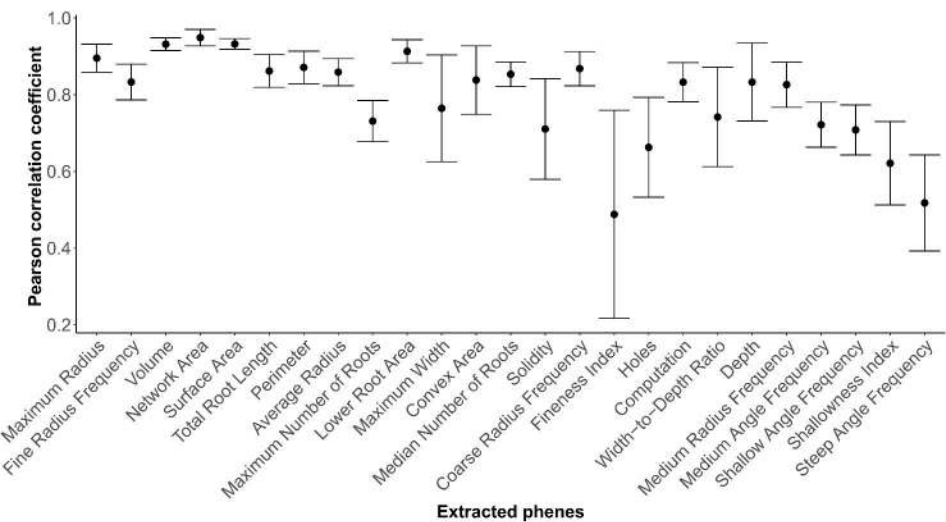


A



B





Factors Residual Camera Block Genotype

